

## MOMENTO ANGULAR ORBITAL EM COORDENADAS ESFÉRICAS

Notas de aula de Mecânica Quântica I

Marcus A.M. de Aguiar - 19/Agosto/2015

A transformação de coordenadas cartesianas para esféricas é dada por

$$\begin{aligned}x &= r \sin \theta \cos \phi \\y &= r \sin \theta \sin \phi \\z &= r \cos \theta\end{aligned}\tag{1}$$

e a transformação inversa é

$$\begin{aligned}r &= \sqrt{x^2 + y^2 + z^2} \\ \tan \theta &= \sqrt{x^2 + y^2}/z \\ \tan \phi &= y/x.\end{aligned}\tag{2}$$

Em coordenadas cartesianas os operadores de momento angular são dados por:

$$\begin{aligned}L_x &= -i\hbar(y\partial/\partial z - z\partial/\partial y) \\ L_y &= -i\hbar(z\partial/\partial x - x\partial/\partial z) \\ L_z &= -i\hbar(x\partial/\partial y - y\partial/\partial x).\end{aligned}\tag{3}$$

Para ilustrar o cálculo desses operadores em coordenadas esféricas faremos o caso  $L_z$ . As derivadas  $\partial/\partial x$  e  $\partial/\partial y$  são escritas como:

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi}$$

e

$$\frac{\partial}{\partial y} = \frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial y} \frac{\partial}{\partial \phi}.$$

As derivadas das coordenadas esféricas em relação às cartesianas podem ser obtidas derivando implicitamente ambos os lados das equações 2 em relação a  $x$ ,  $y$  ou  $z$ :

$$\frac{\partial r}{\partial x} = \frac{x}{r} = \sin \theta \cos \phi$$

$$\frac{1}{\cos^2 \theta} \frac{\partial \theta}{\partial x} = \frac{x}{\sqrt{x^2 + y^2} z} = \frac{\cos \phi}{r \cos \theta} \quad \text{ou} \quad \frac{\partial \theta}{\partial x} = \frac{\cos \theta \cos \phi}{r}$$

$$\frac{1}{\cos^2 \phi} \frac{\partial \phi}{\partial x} = -\frac{y}{x^2} = -\frac{\sin \phi}{r \sin \theta \cos^2 \phi} \quad \text{ou} \quad \frac{\partial \phi}{\partial x} = -\frac{\sin \phi}{r \sin \theta}.$$

Fazendo o mesmo processo com as derivadas em relação a  $y$  obtemos

$$\frac{\partial r}{\partial y} = \sin \theta \sin \phi$$

$$\frac{\partial \theta}{\partial y} = \frac{\cos \theta \sin \phi}{r}$$

$$\frac{\partial \phi}{\partial y} = \frac{\cos \phi}{r \sin \theta}.$$

Voltando à equação (3) para  $L_z$  temos:

$$x \frac{\partial}{\partial x} = r \sin \theta \cos \phi \left( \sin \theta \sin \phi \frac{\partial}{\partial r} + \frac{\cos \theta \sin \phi}{r} \frac{\partial}{\partial \theta} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \quad (4)$$

e

$$y \frac{\partial}{\partial x} = r \sin \theta \sin \phi \left( \sin \theta \cos \phi \frac{\partial}{\partial r} + \frac{\cos \theta \cos \phi}{r} \frac{\partial}{\partial \theta} - \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi} \right). \quad (5)$$

Subtraindo (5) de (4) e multiplicando por  $-i\hbar$  obtemos  $L_z$ . Os dois primeiros termos de cada equação se cancelam e os últimos termos se somam:

$$L_z = -i\hbar(\cos^2 \phi \frac{\partial}{\partial \phi} + \sin^2 \phi \frac{\partial}{\partial \phi}) = -i\hbar \frac{\partial}{\partial \phi}. \quad (6)$$

O cálculo de  $L_x$  e  $L_y$  é completamente análogo e resulta em

$$L_x = i\hbar(\sin \phi \frac{\partial}{\partial \theta} + \frac{\cos \phi}{\tan \theta} \frac{\partial}{\partial \phi}) \quad (7)$$

e

$$L_y = i\hbar(-\cos \phi \frac{\partial}{\partial \theta} + \frac{\sin \phi}{\tan \theta} \frac{\partial}{\partial \phi}). \quad (8)$$

Os operadores  $L_+$  e  $L_-$  também podem ser calculados:

$$L_+ = \hbar e^{i\phi} \left( \frac{\partial}{\partial \theta} + \frac{i}{\tan \theta} \frac{\partial}{\partial \phi} \right) \quad (9)$$

$$L_- = (L_+)^\dagger = \hbar e^{-i\phi} \left( -\frac{\partial}{\partial \theta} + \frac{i}{\tan \theta} \frac{\partial}{\partial \phi} \right). \quad (10)$$

Fica como exercício provar essas equações, principalmente a última relação para  $L_-$ .

Finalmente calculamos  $L^2$ . Começamos com  $L_x^2$ :

$$\begin{aligned}
L_x^2 &= -\hbar^2 \left( \sin \phi \frac{\partial}{\partial \theta} + \frac{\cos \phi}{\tan \theta} \frac{\partial}{\partial \phi} \right) \left( \sin \phi \frac{\partial}{\partial \theta} + \frac{\cos \phi}{\tan \theta} \frac{\partial}{\partial \phi} \right) \\
&= -\hbar^2 \left( \sin^2 \phi \frac{\partial^2}{\partial \theta^2} - \frac{\sin \phi \cos \phi}{\tan^2 \theta \cos^2 \theta} \frac{\partial}{\partial \phi} + 2 \frac{\sin \phi \cos \phi}{\tan \theta} \frac{\partial^2}{\partial \phi \partial \theta} + \frac{\cos^2 \phi}{\tan \theta} \frac{\partial}{\partial \theta} - \right. \\
&\quad \left. \frac{\sin \phi \cos \phi}{\tan^2 \theta} \frac{\partial}{\partial \phi} + \frac{\cos^2 \phi}{\tan^2 \theta} \frac{\partial^2}{\partial \phi^2} \right).
\end{aligned}$$

Da mesma forma obtemos:

$$\begin{aligned}
L_y^2 &= -\hbar^2 \left( -\cos \phi \frac{\partial}{\partial \theta} + \frac{\sin \phi}{\tan \theta} \frac{\partial}{\partial \phi} \right) \left( -\cos \phi \frac{\partial}{\partial \theta} + \frac{\sin \phi}{\tan \theta} \frac{\partial}{\partial \phi} \right) \\
&= -\hbar^2 \left( \cos^2 \phi \frac{\partial^2}{\partial \theta^2} + \frac{\sin \phi \cos \phi}{\tan^2 \theta \cos^2 \theta} \frac{\partial}{\partial \phi} - 2 \frac{\sin \phi \cos \phi}{\tan \theta} \frac{\partial^2}{\partial \phi \partial \theta} + \frac{\sin^2 \phi}{\tan \theta} \frac{\partial}{\partial \theta} + \right. \\
&\quad \left. \frac{\sin \phi \cos \phi}{\tan^2 \theta} \frac{\partial}{\partial \phi} + \frac{\sin^2 \phi}{\tan^2 \theta} \frac{\partial^2}{\partial \phi^2} \right)
\end{aligned}$$

e

$$L_z^2 = -\hbar^2 \frac{\partial^2}{\partial \phi^2}.$$

Somando tudo obtemos finalmente

$$L^2 = -\hbar^2 \left( -\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right).$$