

Cálculo variacional,

Ideia: determinar máximos/minimos

pt 1 função $f = f(x)$: $\frac{df}{dx} = 0 \rightarrow$ solução eq. = pto $x = x_0$

$$\frac{df}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

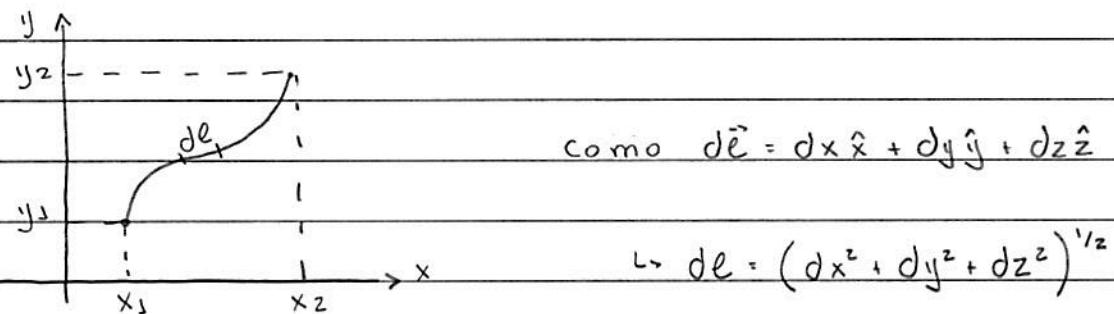
pt 1 funcional $f = f[y(x), y'(x), x]$: f é uma função das funções $y = y(x)$, $y' = y'(x)$ e da variável x .

Nesse caso,

$$\text{defini-se } J \equiv \int_{x_0}^{x_1} f[y, y', x] dx$$

$\delta J = 0 \rightarrow$ solução eq. = função $y = y(x)$!

Ex. 1: determinar curva $y = y(x)$ que corresponde à menor distância entre os pts (x_1, y_1) e (x_2, y_2) .



Nesse caso, é necessário considerar:

$$L = \int_1^2 dE = \int_1^2 (dx^2 + dy^2)^{1/2} : \text{comprimento curva } y = y(x) !$$

como $y = y(x)$, podemos considerar

$$dl = (dx^2 + dy^2)^{1/2} = dx \left(1 + \left(\frac{dy}{dx} \right)^2 \right)^{1/2} = dx \left(1 + y'(x) \right)^{1/2}$$

$$\hookrightarrow L = \int_{x_1}^{x_2} dx \underbrace{\left(1 + y'^2(x) \right)^{1/2}}_{\{I,y'\}} \quad (146.1.0)$$

$\{I,y'\}$: funcional

Q.: Qual $y = y(x)$ tal que L é minímo?

caso geral:

$$J = \int_{x_1}^{x_2} dx f[y(x), y'(x), x] ; \quad y = y(x) \quad (146.1)$$

variável independente
 " dependente

* problema: determinar $y = y(x)$ tal que J é um extremo (máximo/minímo)

hipótese: $y = y(x)$ (a ser determinada) é extremo J ;

definindo: $Y(\alpha, x) = y(x) + \alpha \varphi(x)$: variação w.r.t.

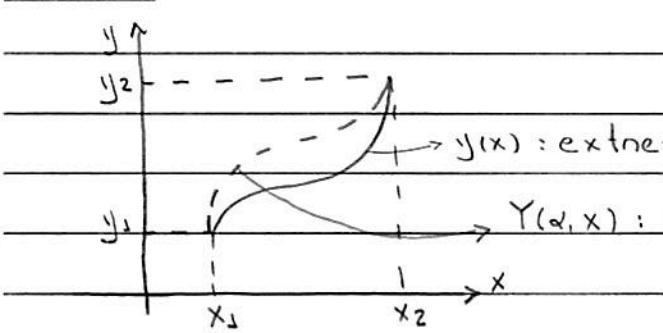
curva "ótima" $y = y(x)$

$$\text{onde } \varphi(x_1) = \varphi(x_2) = 0$$

(146.2)

$$\hookrightarrow Y(\alpha, x_1) = y(x_1) \text{ e } Y(\alpha, x_2) = y(x_2)$$

α : parâmetro



$y(x)$: extremo
 $Y(\alpha, x)$: variação

$$\hookrightarrow \text{Eq. (146.1)} : J = J(\alpha) = \int_{x_1}^{x_2} dx f [Y(\alpha, x), Y'(\alpha, x), x] \quad (147.1)$$

* condição (necessária) pr extremo: $\frac{\partial J}{\partial \alpha} \Big|_{\alpha=0} = 0 \quad (147.2)$

$$\begin{aligned} \hookrightarrow \frac{\partial J}{\partial \alpha} &= \frac{\partial}{\partial \alpha} \int_{x_1}^{x_2} dx f [Y, Y', x] = \int_{x_1}^{x_2} dx \left(\underbrace{\frac{\partial f}{\partial Y} \frac{\partial Y}{\partial \alpha} + \frac{\partial f}{\partial Y'} \frac{\partial Y'}{\partial \alpha}}_{Q} \right) \\ &\text{pois os limites} \quad \leftarrow \quad Q = \frac{dQ}{dx} \\ &\text{de integração} \\ &\text{são fixos!} \end{aligned}$$

$$= \int_{x_1}^{x_2} \underbrace{\frac{\partial f}{\partial Y} Q + \frac{\partial f}{\partial Y'} \frac{dQ}{dx}}_{\sim} dx$$

$$- \frac{d}{dx} \left(\frac{\partial f}{\partial Y'} \right) Q + \underbrace{\frac{d}{dx} \left(Q \frac{\partial f}{\partial Y'} \right)}_{=0}$$

$$= 0, \text{ pois } Q(x_1) = Q(x_2) = 0$$

$$= \int_{x_1}^{x_2} dx \left[\frac{\partial f}{\partial Y} - \frac{d}{dx} \left(\frac{\partial f}{\partial Y'} \right) \right] Q(x) \quad (147.3)$$

(I)

Como $Q(x)$ é sf, a condição $\frac{\partial J}{\partial \alpha} \Big|_{\alpha=0} = 0$

$\hookrightarrow (I) = 0$ e $Y(0, x) = y(x)$, i.e.,

$$\frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) = 0 : \text{Equação de Euler-Lagrange} \quad (148.1)$$

Resumo: determinação determinação $y = y(x)$
extremo Eq. (146.3) ~ a partir Eq. (148.1)

Ex. 1: continuação,

nesse caso, o funcional f é dado pela Eq. (146.1.0),

$$f[y] = \int (1 + y'^2(x))^{1/2}$$

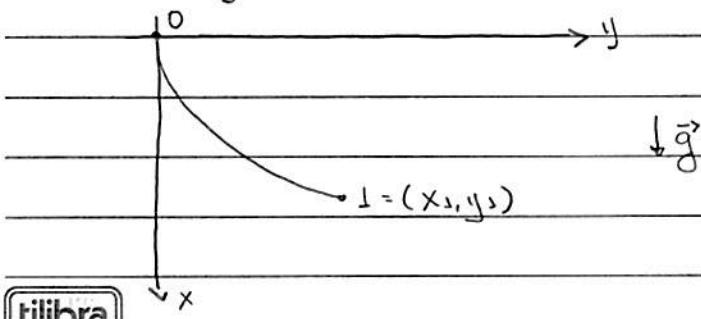
$$\hookrightarrow \frac{\partial f}{\partial y} = 0 \quad e \quad \frac{\partial f}{\partial y'} = \frac{y'}{(1+y'^2)^{1/2}}$$

$$\text{Eq. (148.1)}: \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) = 0 \rightarrow \frac{y'}{(1+y'^2)^{1/2}} = C = \text{cte}$$

$$\hookrightarrow y = ax + b$$

Obs.: determinação $a, b \sim$ pts inicial (x_1, y_1) e final (x_2, y_2) .

Ex. 2: Ex. 6.2, Manion: considerar partícula massa m sob $\vec{F} = m\vec{g}$, movimento plano xy entre pts (x_0, y_0) e (x_1, y_1) ⊕ condição inicial $\vec{v}(t_0) = 0$; determinar trajetória correspondente ao menor $\Delta t = t_1 - t_0$.



Hipótese: $(x_0, y_0) = (0, 0)$

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nesse caso: $\Delta t = t_1 - t_0 = \int_0^1 \frac{dx}{\sqrt{1+y'^2}}$

como: $dx = \sqrt{dx^2 + dy^2} = dx \sqrt{1+y'^2}$; $y = y(x)$ (J49.1)
 $y' = \frac{dy}{dx}$

conservação energia total $\rightarrow v = \sqrt{2g x}$ (J49.2)
 (veja abaixo)

$\hookrightarrow \Delta t = t_1 - t_0 = \frac{1}{\sqrt{2g}} \int_0^{x_1} dx \sqrt{\frac{1+y'^2}{x}}$

notar a forma
 $= f[y', x]$: do funcional!

como:

$$\frac{\partial f}{\partial y} = 0 \quad e \quad \frac{\partial f}{\partial y'} = \frac{y'}{\sqrt{x(1+y'^2)}}$$

\hookrightarrow Eq. (J48.1): $\frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) = 0 \rightarrow \frac{\partial f}{\partial y'} = \frac{y'}{\sqrt{x(1+y'^2)}} = cte = \frac{1}{\sqrt{2a}}$

1 exercício $\rightarrow y'^2 = \frac{x^2}{(2a-x)x} \rightarrow y = \int dx \frac{x}{\sqrt{2ax-x^2}}$

Se $x = a(1-\cos\theta)$

1 exercício $\rightarrow y = \int d\theta a(1-\cos\theta) = a(\theta - \sin\theta) + C_1$

$\hookrightarrow x = x(\theta) = a(1-\cos\theta)$: eq. paramétrica
 $y = y(\theta) = a(\theta - \sin\theta) + C_1$ da trajetória

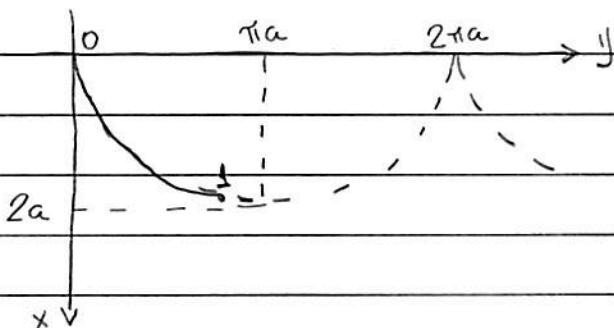
Lembra: determinação ~ pós $(x_0, y_0) = 0$ e
 ctos C_1 e a (x_1, y_1)

notam: $\theta = 0 \rightarrow x = 0 \rightarrow y = 0 : y(0) = 0 \rightarrow C_3 = 0 !$

$$\hookrightarrow x = x(\theta) = a(1 - \cos\theta)$$

$$y = y(\theta) = a(\theta - \sin\theta) : \text{eq. paramétrica ciclóide}$$

$$(\theta = \pi) \quad (\theta = 2\pi)$$



Obs.:

(i) brachistochrone problem; brachistas: shortest chronos : time

(ii) Eq. (149.1): a escolha $y = y(x)$ não é única,
veja exemplo geodésica abaixo

(iii) Eq. (149.2):

$$F_x = mg \rightarrow U(x) - U(0) = - \int_0^x mg dx' = -mgx$$

$$\hookrightarrow E = U(x=0) = 0 = T + U(x) = \frac{1}{2}mv^2 - mgx = 0 \rightarrow v = \sqrt{2gx}$$

• Alternative p/ a determinação de $y = y(x)$: interessante
p/ funções da forma $f = f[y, y']$.

inicial: considerar caso geral $f = f[y, y', x]$

$$\hookrightarrow \frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} + \frac{\partial f}{\partial x}$$

$$= \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' + \frac{\partial f}{\partial x}$$

$$\frac{d}{dx} \left(y' \frac{\partial f}{\partial y'} \right) - y' \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right)$$

$$\hookrightarrow \frac{\partial f}{\partial x} = \frac{\partial f}{\partial x} + \frac{d}{dx} \left(y' \frac{\partial f}{\partial y'} \right) + \underbrace{y' \left(\frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) \right)}_{= 0, \text{ Eq. (148.1)}}$$

$$\hookrightarrow \frac{\partial f}{\partial x} - \frac{d}{dx} \left(y' \frac{\partial f}{\partial y'} \right) = 0$$

notam: se $f = f[y, y'] \Rightarrow \frac{\partial f}{\partial x} = 0$

$$\hookrightarrow f - y' \frac{\partial f}{\partial y'} = \text{cte} \quad (151.1)$$

Ex. 3: Ex. 6.4, Manion: determinar curva que corresponde à menor distância entre os pts P_1 e P_2 ;
curva C superfície: geodésica.

Hipótese: superfície = esfera radio a .

Nesse caso, é necessário considerar:

$$L = \int_1^2 ds \quad (151.2)$$

$$d\vec{r} = dn\hat{n} + n d\theta \hat{\theta} + n \sin\theta d\varphi \hat{\varphi} : \text{pg. 50.}$$

$$\hookrightarrow dl = \left(dn^2 + n^2 d\theta^2 + n^2 \sin^2\theta d\varphi^2 \right)^{1/2}$$

$$\text{como } n=a=\text{cte} \rightarrow dl = \left(a^2 d\theta^2 + a^2 \sin^2\theta d\varphi^2 \right)^{1/2}$$

considerando a possível escolha $\theta = \theta(\varphi)$, i.e., φ é a variável independente

$$\hookrightarrow dl = ad\varphi \left(\theta'^2 + \sin^2\theta \right)^{1/2}; \quad \theta' = d\theta/d\varphi$$

Eq. (151.2) :

$$L = a \int_1^2 d\varphi \underbrace{\left(\theta'^2 + \sin^2\theta \right)^{1/2}}_{f[\theta, \theta']}$$

$$\hookrightarrow \frac{\partial f}{\partial \theta} = \frac{\sin\theta \cos\theta}{\left(\theta'^2 + \sin^2\theta \right)^{1/2}} \quad , \quad \frac{\partial f}{\partial \theta'} = \frac{\theta'}{\left(\theta'^2 + \sin^2\theta \right)^{1/2}}$$

$$\text{Eq. (148.3)}: \frac{\sin\theta \cos\theta}{\left(\theta'^2 + \sin^2\theta \right)^{1/2}} - \frac{d}{d\varphi} \left(\frac{\theta'}{\left(\theta'^2 + \sin^2\theta \right)^{1/2}} \right) = 0$$

· alternativa determinação $\theta = \theta(\varphi)$: via Eq. (151.1);

$$f - y' \frac{\partial f}{\partial y'} = \left(\theta'^2 + \sin^2\theta \right)^{1/2} - \frac{\theta'^2}{\left(\theta'^2 + \sin^2\theta \right)^{1/2}} = \text{cte} \equiv b$$

$$\text{exercício} \rightarrow b\theta' - b \frac{d\theta}{d\varphi} = \sin\theta (\sin^2\theta - b^2)$$

$$\hookrightarrow \frac{d\varphi}{d\theta} = \frac{b}{\sin\theta (\sin^2\theta - b^2)^{1/2}} = \frac{b \csc^2\theta}{(1 - b^2 \csc^2\theta)^{1/2}} \quad (152.1)$$

$$\varphi = \int d\theta \frac{b \csc^2 \theta}{(1 - b^2 \csc^2 \theta)^{1/2}}$$

exercicio : mostrem que

$$\varphi = -\frac{b}{2} \int \frac{dx}{(-b^2 x^2 + (1+b^2)x - 1)^{1/2}} ; \quad t = \frac{1}{\sin \theta} \quad e \quad x = t^2$$

$$= \frac{1}{2} \sin^{-1} \left(-2 \frac{b^2}{1-b^2} \frac{1}{\sin^2 \theta} + \frac{(1+b^2)}{(1-b^2)} \right) + C$$

$$\text{se } C = 2\alpha - \pi/2 \quad e \quad \beta^2 = \frac{1-b^2}{b^2}$$

$$\hookrightarrow \beta \sin(\varphi - \alpha) = \cot \theta \quad (153.1)$$

notam : Eq. (153.1) pode ser escrita como :

$$\underbrace{\beta \cos \alpha}_{\equiv A} (\underbrace{a \sin \theta \sin \varphi}_{y}) - \underbrace{\beta \sin \alpha}_{\equiv B} (\underbrace{a \sin \theta \cos \varphi}_{x}) = \underbrace{a \cos \theta}_{z}$$

$$\hookrightarrow Ay - Bx = z : \text{eq. pleno ;}$$

origem O (centro da esfera) \in pleno

\hookrightarrow geodésica = intersecção pleno / esfera = "grande círculo"

Obs. : cte A e B \sim pts P₁ e P₂ !

alternativa via Eq. (151.1) :

considerando $\varphi = \varphi(\theta)$, temos que

$$d\ell = a (\sin^2 \theta + \sin^2 \theta d\varphi^2)^{1/2} = a d\theta (1 + \sin^2 \theta \varphi'^2)^{1/2}; \quad \varphi' = \frac{d\varphi}{d\theta}$$

$$\hookrightarrow \text{Eq. (151.2)} : L = a \int_1^2 d\theta (1 + \sin^2 \theta \varphi'^2)^{1/2}$$

$f[\varphi', \theta]$

\searrow variável independente!

$$\hookrightarrow \frac{\partial f}{\partial \varphi} = 0 \quad e \quad \frac{\partial f}{\partial \varphi'} = \frac{\varphi'}{(1 + \sin^2 \theta \varphi'^2)^{1/2}} \sin^2 \theta$$

$$\text{Eq. (148.1)} : \frac{d}{d\theta} \left(\frac{\partial f}{\partial \varphi'} \right) = 0 \rightarrow \frac{\partial f}{\partial \varphi'} = \text{cte} \equiv b$$

$$\hookrightarrow \frac{\sin^2 \theta \varphi'}{(1 + \sin^2 \theta \varphi'^2)^{1/2}} = b \quad \text{exercício} \rightarrow \text{Eq. (152.1)} \quad (154.1)$$

- solução Eq. (152.1)

hipótese : pto $P_0 = (0,0,a)$: $n = a$ e $\theta = 0$

$$\text{notar: } \frac{df}{d\theta} \Big|_{\theta=0} \rightarrow +\infty$$

p/ $\varphi' < +\infty$ a cte b deve ser nula

$b = 0 \rightarrow \varphi' = 0 \rightarrow \varphi = \text{cte}$: equação plena;

ouigem o é plena!

• consideram: f funcional de várias variáveis dependentes

$$y_i = y_i(x).$$

inicial: caso particular

$$f = f [y_1(x), y'_1(x), y_2(x), y'_2(x), x] \quad (155.1)$$

nesse caso, Eq (146.1) :

$$J = \int_{x_1}^{x_2} dx f [y_1, y'_1, y_2, y'_2, x] \quad (155.2)$$

de modo análogo ao caso $f = f [y, y', x]$, define-se

$$Y_1(\alpha, x) = y_1(x) + \alpha \eta_1(x) ; \quad \eta_1(x_1) = \eta_1(x_2) = 0$$

$$Y_2(\alpha, x) = y_2(x) + \alpha \eta_2(x) ; \quad \eta_2(x_1) = \eta_2(x_2) = 0$$

$$\hookrightarrow \frac{\partial J}{\partial \alpha} = \int_{x_1}^{x_2} dx \left[\frac{\partial f}{\partial Y_1} - \frac{d}{dx} \left(\frac{\partial f}{\partial Y'_1} \right) \eta_1 + \left[\frac{\partial f}{\partial Y_2} - \frac{d}{dx} \left(\frac{\partial f}{\partial Y'_2} \right) \right] \eta_2 \right]$$

como $\eta_1(x)$ e $\eta_2(x)$ são independentes a condição

$$\Rightarrow \left. \frac{\partial J}{\partial \alpha} \right|_{\alpha=0} = 0$$

$$\hookrightarrow \frac{\partial f}{\partial y_i} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'_i} \right) = 0 ; \quad i = 1, 2 \quad (155.3)$$

caso geral: $f = f [y_1, y_2, \dots, y_n, y'_1, y'_2, \dots, y'_n, x] = f [y_i, y'_i, x]$

$$\hookrightarrow \frac{\partial f}{\partial y_i} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'_i} \right) = 0 ; \quad i = 1, 2, \dots, n \quad (156.1)$$

Ex. 1: solução alternativa,

consideram $x = x(t)$: eq. paramétrica curva

$$y = y(t)$$

$$\hookrightarrow de = \left(dx^2 + dy^2 \right)^{1/2} dt = dt \underbrace{\left(x'^2 + y'^2 \right)^{1/2}}_{x' = dx/dt} ; \quad y' = dy/dt$$

$$L = \int_1^2 de = \int_{t_1}^{t_2} dt \underbrace{\left(x'^2 + y'^2 \right)^{1/2}}_{f[x', y']}$$

$$\text{como } \frac{\partial f}{\partial x} = 0 \quad \frac{\partial f}{\partial x'} = \frac{x'}{\left(x'^2 + y'^2 \right)^{1/2}}$$

$$\frac{\partial f}{\partial y} = 0 \quad \frac{\partial f}{\partial y'} = \frac{y'}{\left(x'^2 + y'^2 \right)^{1/2}}$$

$$\text{Eq. (156.1)} : \quad \frac{d}{dt} \left(\frac{\partial f}{\partial x'} \right) = 0 \rightarrow \frac{x'}{\left(x'^2 + y'^2 \right)^{1/2}} = C_1$$

$$\frac{d}{dt} \left(\frac{\partial f}{\partial y'} \right) = 0 \rightarrow \frac{y'}{\left(x'^2 + y'^2 \right)^{1/2}} = C_2$$

$$\hookrightarrow \frac{y'}{x'} = ct = a = \frac{dy}{dt} \cdot \frac{dt}{dx} = \frac{dy}{dx} = a$$

$$\hookrightarrow y = ax + b .$$

• Determinação extrema sob vínculo,

consideram $f = f[y(x), y'(x), z(x), z'(x), x]$

e $g[y, z, x] = 0$: eq. do vínculo (157.1)

→ \exists relação entre as funções $y = y(x)$ e $z = z(x)$!

Ex.: geodésica,

como curva C esfera radio a

$$\hookrightarrow x^2 + y^2 + z^2 = a^2 \rightarrow g = x^2 + y^2 + z^2 - a^2 = 0$$

$$\text{ou } r = a \rightarrow g = r - a = 0$$

Eq. (155.2) :

$$J = \int_{x_1}^{x_2} dx f[y, y', z, z', x]$$

verifica-se que (veja abaixo)

$$\left. \frac{\partial J}{\partial \alpha} \right|_{\alpha=0} = 0 \rightarrow \frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) + \lambda(x) \frac{\partial g}{\partial y} = 0$$

(157.2)

$$\frac{\partial f}{\partial z} - \frac{d}{dx} \left(\frac{\partial f}{\partial z'} \right) + \lambda(x) \frac{\partial g}{\partial z} = 0$$

→ multiplicador

de Lagrange

notam:

Eq. (157.2) \oplus vínculo : 3 equações

3 funções a determinar: $y = y(x)$, $z = z(x)$,
 $\lambda = \lambda(x)$.

• caso geral:

$$f = f[y_i, y'_i, x] ; i = 1, 2, \dots, n$$

$$\frac{\partial f}{\partial y_i} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'_i} \right) + \sum_{j=1}^m \lambda_j \frac{\partial g_j}{\partial y_i} = 0$$

(158.1)

$$g_j[y_i, x] = 0 , j = 1, 2, \dots, m$$

• vamos verificar Eq. (157.2),

de modo análogo ao caso particular (155.1), define-se

$$Y(\alpha, x) = y(x) + \alpha \eta_1(x) ; \eta_1(x_1) = \eta_1(x_2) = 0$$

$$Z(\alpha, x) = z(x) + \alpha \eta_2(x) ; \eta_2(x_1) = \eta_2(x_2) = 0$$

$$\hookrightarrow \frac{\partial J}{\partial \alpha} = \int_{x_1}^{x_2} dx \left[\frac{\partial f}{\partial Y} - \frac{d}{dx} \left(\frac{\partial f}{\partial Y'} \right) \right] \eta_1 + \left[\frac{\partial f}{\partial Z} - \frac{d}{dx} \left(\frac{\partial f}{\partial Z'} \right) \right] \eta_2 \quad (158.2)$$

* \neq caso anterior, $\eta_1(x)$ e $\eta_2(x)$ não são independentes
 devido ao vínculo (157.1)!

$$\text{Como: } \eta_1 = \frac{\partial Y}{\partial \alpha} ; \eta_2 = \frac{\partial Z}{\partial \alpha}$$

$$\rightarrow \eta_2 = -\eta_1 \frac{\partial g}{\partial Y} \left(\frac{\partial g}{\partial Z} \right)^{-1}$$

$$dg = \frac{\partial g}{\partial Y} \frac{\partial Y}{\partial \alpha} + \frac{\partial g}{\partial Z} \frac{\partial Z}{\partial \alpha} = 0$$

(158.3)

Eq. (158.3) em (158.2) :

$$\frac{\partial J}{\partial \alpha} = \int_{x_1}^{x_2} dx \left[\underbrace{\frac{\partial f}{\partial Y} - \frac{d}{dx} \left(\frac{\partial f}{\partial Y'} \right)}_{(I)} - \underbrace{\left(\frac{\partial f}{\partial Z} - \frac{d}{dx} \left(\frac{\partial f}{\partial Z'} \right) \right) \frac{\partial g}{\partial Y} \left(\frac{\partial g}{\partial Z} \right)^{-1}}_{(II)} \right] \eta_1$$

nesse caso

$$\frac{\partial J}{\partial \alpha} = 0 \rightarrow (I) - (II) \frac{\partial g}{\partial Y} \left(\frac{\partial g}{\partial Z} \right)^{-1} = 0$$

$$\hookrightarrow (I) \left(\frac{\partial g}{\partial Y} \right)^{-1} = (II) \left(\frac{\partial g}{\partial Z} \right)^{-1} \equiv -\lambda(x) \quad (159.1)$$

pois L.H.S. função apenas y e

R.H.S. " " " z !

$$\alpha = 0 \text{ em (159.1)} \rightarrow (157.2) !$$

Ex. 4 : P 6.12, Manion : determinar a geodésica p/ a esfera,
poném considerando explicitamente o vínculo
 $r = a$ = raio da esfera.

$$\text{Ex. 3 : } L = \int_1^2 de$$

$$de = \left(dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\varphi^2 \right)^{1/2}$$

considerando $r = r(\theta)$ e $\varphi = \varphi(\theta)$:

$$L = \int_1^2 d\theta \underbrace{\left(r^2 + r'^2 + r^2 \sin^2 \theta \varphi'^2 \right)^{1/2}}_{f} ; \quad r' = dr/d\theta \quad \varphi' = d\varphi/d\theta$$

$$f = f [r, r', \varphi', \theta]$$

\downarrow variável independente !

e $g[n] = n - a = 0$: eq. do vínculo

$$\text{como : } \frac{\partial f}{\partial n} = \frac{n(1 + \sin^2 \theta \cdot \varphi'^2)}{(n^2 + n'^2 + n^2 \sin^2 \theta \cdot \varphi'^2)^{1/2}} ; \quad \frac{\partial f}{\partial n'} = \frac{n'}{(n^2 + n'^2 + n^2 \sin^2 \theta \cdot \varphi'^2)^{1/2}}$$

$$\frac{\partial f}{\partial \varphi} = 0 \quad \frac{\partial f}{\partial \varphi'} = \frac{n^2 \sin^2 \theta \cdot \varphi'}{(n^2 + n'^2 + n^2 \sin^2 \theta \cdot \varphi'^2)^{1/2}}$$

$$\frac{\partial g}{\partial n} = 1 \quad \frac{\partial g}{\partial \varphi} = 0$$

Eq. (158.1) :

$$n : \frac{n(1 + \sin^2 \theta \cdot \varphi'^2)}{(n^2 + n'^2 + n^2 \sin^2 \theta \cdot \varphi'^2)^{1/2}} - \frac{d}{d\theta} \left(\frac{n'}{(n^2 + n'^2 + n^2 \sin^2 \theta \cdot \varphi'^2)^{1/2}} \right) + \lambda = 0 \quad (160.1)$$

$$\varphi : \frac{n^2 \sin^2 \theta \cdot \varphi'}{(n^2 + n'^2 + n^2 \sin^2 \theta \cdot \varphi'^2)^{1/2}} = cte \quad (160.2)$$

$\hookrightarrow g = n - a = 0$ em (160.2) :

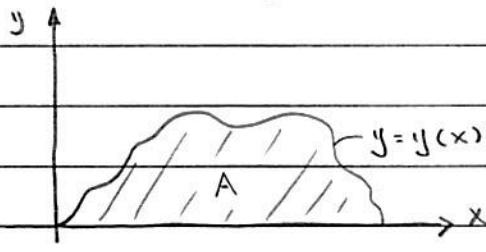
$$\frac{\sin^2 \theta \cdot \varphi'}{(1 + \sin^2 \theta \cdot \varphi'^2)^{1/2}} = cte : \text{Eq. (159.1)} \rightarrow \varphi = cte$$

$\hookrightarrow g = n - a = 0$ e $\varphi = cte$ em (160.1) :

$$\lambda(\theta) = -(1 + \sin^2 \theta \cdot \varphi'^2)^{1/2}$$

Obs. : $\lambda \sim$ força de vínculo na mecânica Lagrangiana
(veja, cap. 7!).

Ex. 5 : Ex. 6.6, Manion : considerar conda comprimento $\leq L$, extremidade fixa na origem 0; determinar curva $y = y(x)$ tal que a área A seja máxima.



nesse caso : $A = \int_0^{x_1} y dx$ (161.1)

como : $de^2 = dx^2 + dy^2$ e escolhendo y como variável dependente

$$\rightarrow dx = (de^2 - dy^2)^{1/2} = de(1 - y'^2)^{1/2}; \quad y = y(e)$$

$$y' = dy/de$$

Eq. (161.1) : $A = \int_0^e y(1 - y'^2)^{1/2} de$

$$f = f[y, y']$$

como $df/de = 0$, vamos considerar Eq. (151.5) :

$$\frac{f - y' df}{dy'} = \frac{y(1 - y'^2)^{1/2} - y'y(1/2)(-2y')}{(1 - y'^2)^{1/2}} = a = cte$$

$$\rightarrow y(1 - y'^2) - yy'^2 = a(1 - y'^2)^{1/2} \rightarrow y' = \frac{dy}{de} = \sqrt{\frac{1 - y^2/a^2}{y}}$$

$$\rightarrow de = \frac{dy}{\sqrt{1 - y^2/a^2}} \rightarrow a \sin^{-1}(y/a) = e + cte$$

$$\rightarrow y = a \sin(e/a) + b$$

como $de^2 = dx^2 + dy^2 \rightarrow 1 = \left(\frac{dx}{de}\right)^2 + \left(\frac{dy}{de}\right)^2$

$$1 = \left(\frac{dx}{de}\right)^2 + \cos^2 \alpha \rightarrow \frac{dx}{de} = \pm \sin \alpha$$

$$\hookrightarrow x = +a \cos \alpha + C$$

$$\hookrightarrow x = x(\alpha) = a \cos \alpha + C$$

: eq. paramétrica $y = y(x)$.

$$y = y(\alpha) = a \sin \alpha + b$$

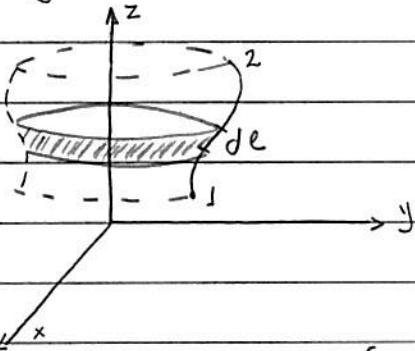
como $(x - c)^2 + (y - b)^2 = a^2$: semi-círculo : raio a

centro (c, b)

nesse caso: $\pi a = L$

$$b = 0 \text{ e } c = a = L/\pi.$$

Ex. 6: Ex. 6.3, Manian: determinar curva $z = z(y)$ t.c. que
a área da superfície de revolução (em torno eixo \hat{z})
seja mínima.



curva C no plano yz

$P_1 = (0, y_1, z_1) \in P_2 = (0, y_2, z_2)$: fixos

$$\text{nesse caso: } A = \int dA = \int 2\pi y \, de$$

como: $de = (dy^2 + dz^2) \text{ e considerando } z = z(y)$

$$\hookrightarrow dA = 2\pi y \, dy \sqrt{1 + z'^2} ; z' = dz/dy$$

$$\hookrightarrow A = 2\pi \int_{y_1}^{y_2} dy \underbrace{y}_{f = f[z', y]} \underbrace{(1 + z'^2)^{\frac{1}{2}}}_{\text{variável independente.}}$$

como $\frac{\partial f}{\partial z} = 0$ e $\frac{\partial f}{\partial z'} = \frac{yz'}{\sqrt{1 + z'^2}}$

$$\text{Eq. (148.3)}: d \left(\frac{\partial f}{\partial z'} \right) = 0 \rightarrow \frac{yz'}{\sqrt{1 + z'^2}} = a = \text{cte}$$

$$\hookrightarrow z' = \frac{dz}{dy} = \frac{a}{\sqrt{y^2 - a^2}} \quad \text{exercício} \rightarrow z = a \cosh^{-1}(y/a) + b$$

ou $y = a \cosh(\frac{z-b}{a})$: catenária

Lembrem: ctes a e b ~ ptos fixos $P_1 = (0, y_1, z_1)$ e $P_2 = (0, y_2, z_2)$.

sobre a notação δ :

$$\text{Eq. (147.3)}: \frac{\partial J}{\partial \alpha} = \int_{x_1}^{x_2} dx \left(\frac{\partial f}{\partial Y} - \frac{d}{dx} \left(\frac{\partial f}{\partial Y} \right) \right) \frac{\partial Y}{\partial \alpha} \quad (163.1)$$

Eq. (163.1) pode ser escrita como

$$\frac{\partial J}{\partial \alpha} d\alpha = \int_{x_1}^{x_2} dx \left(\frac{\partial f}{\partial Y} - \frac{d}{dx} \left(\frac{\partial f}{\partial Y} \right) \right) \frac{\partial Y}{\partial \alpha} d\alpha$$

definindo: $\delta J = \frac{\partial J}{\partial \alpha} d\alpha$

$$\delta Y = \frac{\partial Y}{\partial \alpha} d\alpha$$

$$\hookrightarrow SJ = \int_{x_1}^{x_2} dx \left(\frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) \delta y \right)$$

vamos determinar Eq. (148.1) utilizando a notação δ ,

$$SJ = \delta \int_{x_1}^{x_2} dx f[y, y', x] = \int_{x_1}^{x_2} dx \delta f$$

→ limites de integração fixos

$$= \int_{x_1}^{x_2} dx \left(\frac{\partial f}{\partial y} \delta y + \frac{\partial f}{\partial y'} \delta y' \right) \quad (164.1)$$

como $\delta y' = \delta \left(\frac{dy}{dx} \right) = \frac{d}{dx} \delta y$ em (164.1) \oplus integração por partes

$$\hookrightarrow SJ = \int_{x_1}^{x_2} dx \left(\frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) \delta y \right)$$

a condição $SJ = 0 \rightarrow$ Eq. (148.1)