

Formulação Lagrangiana e Hamiltoniana,

ideia: introdução formalismos Lagrangiano e Hamiltoniano p/

- (i) partícula carga q sob campos EM;
- (ii) campo EM.

• Ref.: Secs. 12.1-12.3, 12.7 e

inicial: revisão mecânica clássica, 12.10, Jackson

(i) formalismo Lagrangiano,

considerar: sistema N -partículas massas m_i , descritas pelas coordenadas generalizadas

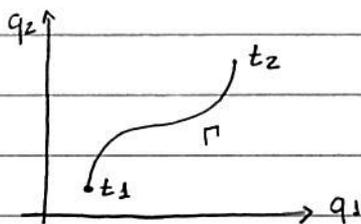
$$q_1, q_2, \dots, q_s, \quad s = 3N - K$$

↳ # vínculos!

estado do sistema = pto no espaço de configurações
(espaço dimensão = s , definido pelas coordenadas generalizadas)

↳ p/ intervalo $\Delta t = t_2 - t_1$: movimento sistema =
= trajetória (curva Γ) no espaço de config.

Ex.: sistema descrito pelas coord. generalizadas q_1 e q_2 ,



mecânica Lagrangiana: baseada no princípio de Hamilton:

o movimento de um sistema no intervalo de tempo

$\Delta t = t_2 - t_1$ e tal que a ação S ,

$$S = \int_{t_1}^{t_2} dt L(q_j, \dot{q}_j, t) \quad (221.1)$$

é estacionária ($\delta S = 0$) para a trajetória do sistema.

Aqui, $L = T - U$: função Lagrangiana (221.2)

$$q_j = q_j(t)$$

$$\dot{q}_j = \dot{q}_j(t) : \text{velocidades generalizadas}$$

em particular, p/ sistemas conservativos, temos que

$$L = \frac{1}{2} \sum_j m_j \dot{q}_j^2 - U(q_1, q_2, \dots, q_s) \quad (221.3)$$

verifica-se que (veja abaixo).

$$\delta S = 0 \rightarrow \frac{\partial L}{\partial q_j} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) = 0 : \text{Eq. de Lagrange} \quad (221.4)$$

$j = 1, 2, \dots, s = 3N - k$

considerar : coord. generalizadas = coord. cartesianas,

$$\hookrightarrow \text{Eq. (221.3)} : L = \frac{1}{2} \sum_{i=1}^N m_i (\dot{x}_i^2 + \dot{y}_i^2 + \dot{z}_i^2) - U(\vec{r}_1, \vec{r}_2, \dots, \vec{r}_N)$$

$$\hookrightarrow \frac{\partial L}{\partial x_i} = -\frac{\partial U}{\partial x_i} \quad \text{e} \quad \frac{\partial L}{\partial \dot{x}_i} = m_i \dot{x}_i$$

$$\text{Eq. (221.4)} : -\frac{\partial U}{\partial x_i} - m_i \ddot{x}_i = 0 \rightarrow m_i \ddot{x}_i = -\frac{\partial U}{\partial x_i}$$

: eqs. de

e, similar: $m_i \ddot{y}_i = -\frac{\partial U}{\partial y_i}$; $m_i \ddot{z}_i = -\frac{\partial U}{\partial z_i}$ movimento :

2ª Lei Newton

Vamos verificar Eq. (221.4),

considerar: variação $q_j(t) \rightarrow q_j(t) + \delta q_j(t)$ da trajetória sistema
w.r.t. trajetória $q_j(t)$ que corresponde extremo
ação S ⊕ condições: $\delta q_j(t_1) = \delta q_j(t_2) = 0$ (*)

$$\begin{aligned} \hookrightarrow \delta S &= \int_{t_1}^{t_2} dt \delta L = \int_{t_1}^{t_2} dt \left[L[q_j(t) + \delta q_j(t); \dot{q}_j(t) + \delta \dot{q}_j(t); t] - \right. \\ &\quad \left. - L[q_j(t); \dot{q}_j(t); t] \right] \end{aligned}$$

Como, em 1ª ordem em δq_j ,

$$L(q_j + \delta q_j, \dot{q}_j + \delta \dot{q}_j, t) \approx L(q_j, \dot{q}_j, t) + \frac{\partial L}{\partial q_j} \delta q_j + \frac{\partial L}{\partial \dot{q}_j} \delta \dot{q}_j,$$

temos que,

$$\delta S = \int_{t_1}^{t_2} dt \left(\frac{\partial L}{\partial q_j} \delta q_j + \frac{\partial L}{\partial \dot{q}_j} \delta \dot{q}_j \right)$$

$$\text{como } \delta \dot{q}_j = \delta \left(\frac{dq_j}{dt} \right) = \frac{d}{dt} (\delta q_j)$$

$$\begin{aligned} \hookrightarrow \delta S &= \int_{t_1}^{t_2} dt \left(\frac{\partial L}{\partial q_j} \delta q_j + \frac{\partial L}{\partial \dot{q}_j} \frac{d}{dt} \delta q_j \right) \\ &\quad - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) \delta q_j + \frac{\partial L}{\partial \dot{q}_j} \delta q_j \Big|_{t_1}^{t_2} \\ &= 0 \sim (*) \end{aligned}$$

$$\hookrightarrow \delta S = \int_{t_1}^{t_2} dt \left(\frac{\partial L}{\partial q_j} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) \right) \delta q_j = 0$$

como $\delta q_j(t)$ é arbitrário \rightarrow Eq. (221.4)!

notas : $\frac{\partial L}{\partial \dot{x}_i} = m_i \dot{x}_i = p_{x,i}$: componente x, momento linear partícula m_i (222.1)

↳ generalização (222.1) p/ $L = L(q_j, \dot{q}_j, t)$:

$p_j = \frac{\partial L}{\partial \dot{q}_j}$: momento generalizado ou momento canonicamente conjugado (222.2)

(2) formalismo Hamiltoniano,

Lembrar definição função Hamiltoniana, sistema c/ n graus de liberdade :

$$H(p, q, t) = \sum_{j=1}^n \dot{q}_j p_j - L(q, \dot{q}, t) \quad (222.3)$$

onde : $q = (q_1, q_2, \dots, q_n)$: $2n$ variáveis independentes!
 $p = (p_1, p_2, \dots, p_n)$

Lembrar : - Eq. (222.3) : transformada de Legendre
variáveis $(q, \dot{q}, t) \rightarrow (q, p, t)$;

- q_j e p_j : variáveis canonicamente conjugadas.

eqs. de movimento :

$$\left. \begin{aligned} \dot{q}_j &= \frac{\partial H}{\partial p_j} \\ \dot{p}_j &= -\frac{\partial H}{\partial q_j} \end{aligned} \right\} \begin{aligned} &2n \text{ eqs. diferenciais 1}^\circ \text{ ordem:} \\ &\text{Eqs. de Hamilton} \\ &(\text{eqs. canônicas de movimento}) \end{aligned} \quad (222.4)$$

$$\frac{\partial L}{\partial t} = -\frac{\partial H}{\partial t}$$

notas : $\frac{\partial H}{\partial t} = \frac{\partial H}{\partial q_j} \dot{q}_j + \frac{\partial H}{\partial p_j} \dot{p}_j + \frac{\partial H}{\partial t} = -\dot{p}_j \dot{q}_j + \dot{q}_j \dot{p}_j + \frac{\partial H}{\partial t}$ ← Eq. (222.4)

$$L \rightarrow \frac{dH}{dt} = \frac{\partial H}{\partial t} = - \frac{\partial L}{\partial t} :$$

- H depende t apenas explicitamente NOT implicitamente
via q_j e p_j ;

- Se $L = L(q_j, \dot{q}_j) \rightarrow \frac{dH}{dt} = 0 \rightarrow H$: cte de movimento!

• Formulação relativística: partícula sob campo EM,

considerar: partícula massa m , carga q sob campos \vec{E} e \vec{B} ,

Lembrar: (i) Lagnangiana, limite não-relativístico,

$$L = \frac{1}{2} m u^2 - q\phi + \frac{1}{c} q \vec{u} \cdot \vec{A} \quad (223.1)$$

↑
velocidade partícula

(ii) eq. de movimento partícula (215.2), forma covariante,

$$\frac{dP^\alpha}{d\tau} = \frac{1}{c} q F^{\alpha\beta} U_\beta \quad ; \quad P^\alpha = (E/c, \vec{p}) \quad \equiv \quad U^\alpha = (c, c\vec{u}) \quad (223.2)$$

ou componentes

$$\text{espaciais } \underline{\underline{e}} \quad \frac{d\vec{p}}{dt} = q(\vec{E} + \frac{1}{c} \vec{u} \times \vec{B})$$

temporal :

$$\frac{dE}{dt} = q \vec{u} \cdot \vec{E}$$

ideia: determinar Lagnangiana relativística tal que

- eq. de movimento \sim Eqs. (223.2) e

- $\lim v/c \ll 1 \sim$ Eq. (223.1) !

• sobre a Lagnangiana:

postulado (1) \rightarrow ação S deve ser invariante sob transf.

Lonentz pois $SS = 0 \rightarrow$

↳ eqs. de movimento.

↳ é interessante escrever S em termos tempo próprio $d\tau$!

como Eq. (184.2): $dt = \gamma d\tau$, temos que

$$S = \int_{\tau_1}^{\tau_2} d\tau \gamma \mathcal{L} \quad (224.1)$$

como $d\tau$ invariante $\rightarrow \gamma \mathcal{L}$ invariante (escalar) sob
transf. Lorentz!

inicial: consideramos partícula livre,

$$\text{Eq. (223.2): } \frac{dP^\mu}{d\tau} = \frac{d}{d\tau} (mU^\mu) = 0$$

ou

$$\frac{d}{dt} (\gamma m \vec{u}) = 0 \quad \text{e} \quad \frac{dE}{dt} = 0$$

(224.2)

notas:

\mathcal{L} depende: m e \vec{u}

" " " " : \vec{u} , pois sistema apresenta
invariância translacional!

Lembrar invariante de Lorentz relacionado velocidade,

$$\text{Eq. (192.1): } U_\alpha U^\alpha = c^2$$

↳ $\gamma \mathcal{L} \sim U_\alpha U^\alpha = c^2$! De fato, temos que:

$$\gamma \mathcal{L} = -mc^2 \quad \text{ou} \quad \mathcal{L}_{\text{free}} = -\frac{mc^2}{\gamma} = -mc^2 \left(1 - \frac{u^2}{c^2}\right)^{1/2} \quad (224.3)$$

: Lagrangiana relativística
partícula livre!

notas: $\frac{\partial L}{\partial n_i} = 0$ e $\frac{\partial L}{\partial \dot{n}_i} = \frac{\partial L}{\partial u_i} = -\gamma mc^2 \cdot \frac{1}{2} \left(\frac{-2u_i}{c^2} \right) = \gamma m u_i$

\hookrightarrow Eq. de Lagrange (223.4) : $\frac{d}{dt}(\gamma m \vec{u}) = 0$: ok c/ (224.2)

como Eq. (193.3) : $E = \left((pc)^2 + (mc^2)^2 \right)^{1/2}$

$\hookrightarrow \frac{dE}{dt} = \frac{1}{E} \cdot \frac{1}{2} \cdot 2pc^2 \frac{dp}{dt} = 0$, pois $\dot{p} = 0$: ok c/ (224.2)
(225.1)

pois $u/c \ll 1$, temos que

$$L_{\text{free}} = -mc^2 \left(1 - \frac{1}{2} \frac{u^2}{c^2} - \frac{1}{8} \frac{u^4}{c^4} + \dots \right) = -mc^2 + \frac{1}{2} m u^2 + \frac{1}{8} m \frac{u^4}{c^2} + \dots$$

(225.2)

considerar: partícula sob campos \vec{E} e \vec{B} ,

Eq. (223.1) $\rightarrow \gamma L \sim$ produto escalar 4-vetor $A^\alpha = (\Phi, \vec{A})$ e
4-velocidade $U^\alpha = (\gamma c, \gamma \vec{u})$

novamente: invariância translacional exclui $x^\alpha = (x^0, \vec{x})$!

De fato, temos que

$$\gamma L = -mc^2 - \frac{1}{c} q U^\alpha A_\alpha$$

$\hookrightarrow L = -mc^2 \left(1 - \frac{u^2}{c^2} \right)^{1/2} - q\Phi + q \vec{u} \cdot \vec{A}$: (225.3)

: Lagrangiana relativística, partícula
sob campo EM

notas: (i) $p \ll \frac{u}{c} \ll 1$: Eqs. (225.2) e (225.3) \rightarrow (223.1)!

$$(ii) \quad \frac{\partial \mathcal{L}}{\partial n_i} = -q \partial_i \Phi + q \frac{1}{c} u_j \partial_i A_j$$

$$\frac{\partial \mathcal{L}}{\partial n_i} = \frac{\partial \mathcal{L}}{\partial u_i} = -\gamma m c^2 \cdot \frac{1}{2} \cdot \frac{(-2u_i)}{c^2} + \frac{1}{c} q A_i$$

$$\text{Eq. (221.4)}: -q \partial_i \Phi + \frac{1}{c} q u_j \partial_i A_j - \frac{d}{dt} \left(\gamma m u_i + \frac{1}{c} q A_i \right) = 0$$

$$\text{como } \frac{d}{dt} (\gamma m u_i) = \frac{dp_i}{dt}$$

$$\frac{d}{dt} A_i = \frac{\partial A_i}{\partial t} + \vec{u} \cdot \vec{\nabla} A_i = \partial_t A_i + u_j \partial_j A_i$$

$$\hookrightarrow \frac{dp_i}{dt} = q \left(-\partial_i \Phi - \frac{1}{c} \partial_t A_i \right) + \frac{1}{c} q \left(u_j \partial_i A_j - u_j \partial_j A_i \right)$$

$$\text{como } (\vec{u} \times (\vec{\nabla} \times \vec{A}))_i = \epsilon_{ijk} u_j (\vec{\nabla} \times \vec{A})_k = \epsilon_{ijk} \epsilon_{k\alpha\beta} u_j \partial_\alpha A_\beta$$

$$\stackrel{\text{pg. 39.1}}{=} u_j \partial_i A_j - u_j \partial_j A_i$$

$$\hookrightarrow \frac{dp_i}{dt} = q \left(E_i + \frac{1}{c} (\vec{u} \times \vec{B})_i \right) : \text{OK c/ Eq. (223.2) !}$$

$$(iii) \quad \text{Eq. (225.1)}: \frac{dE}{dt} = \frac{c^2}{E} \vec{p} \cdot \frac{d\vec{p}}{dt} = \frac{q c^2}{E} \vec{p} \cdot \left(\vec{E} + \frac{1}{c} \vec{u} \times \vec{B} \right)$$

$$\hookrightarrow \frac{dE}{dt} = q \frac{c^2}{E} \vec{p} \cdot \vec{E} = q \underbrace{\gamma m c^2}_{1} \vec{u} \cdot \vec{E} : \text{OK c/ Eq. (223.2) !}$$

Eqs. (222.2) e (225.3):

$$\pi_i = \frac{\partial L}{\partial u_i} = \gamma m u_i + \frac{1}{c} q A_i = p_i + \frac{1}{c} q A_i \neq p_i = \gamma m u_i$$

↳ $\vec{\pi} = \vec{p} + \frac{1}{c} q \vec{A}$: momento canonicamente conjugado

(227.1)

Eq. (222.3):

$$H = \pi_i u_i - L = \vec{u} \cdot \vec{\pi} - L$$

$$= \vec{u} \cdot \left(\gamma m \vec{u} + \frac{1}{c} q \vec{A} \right) + \frac{mc^2}{\gamma} + q\Phi - q \frac{\vec{u} \cdot \vec{A}}{c}$$

$$= \frac{mc^2}{\gamma} \left(1 + \frac{r^2 u^2}{c^2} \right) + q\Phi = mc^2 \gamma + q\Phi = \mathcal{E} + q\Phi$$

↑ Eq. (193.3)

$$= \left((pc)^2 + m^2 c^4 \right)^{1/2} + q\Phi$$

$$\text{↳ } H = \left((c\vec{\pi} - q\vec{A})^2 + m^2 c^4 \right)^{1/2} + q\Phi : \text{Hamiltoniana} \quad (227.2)$$

relativística,

partícula sob

campo EM

notas: como $H = \mathcal{E} + q\Phi \rightarrow H$: energia total partícula!

Exercício: verificar que Eqs. (222.4) e (227.2) = Eq. (223.2)

$$\text{notas: } (H - q\Phi)^2 = (c\vec{\pi} - q\vec{A})^2 + m^2 c^4$$

$$= c^2 \left(\vec{\pi} - q\vec{A}/c \right)^2 + m^2 c^4$$

comparando c/ Eq. (193.3), podemos definir 4-vetor

$$P^\alpha = \left(\frac{1}{c} (H - q\Phi), \vec{\pi} - \frac{1}{c} q \vec{A} \right)$$

$$= \left(\frac{H}{c}, \vec{\pi} \right) - \frac{1}{c} q (\Phi, \vec{A})$$

$$\equiv \pi^\alpha - \frac{1}{c} q A^\alpha \quad : \quad \text{4-momento canonicamente conjugado} \quad (228.1)$$

: comparan c/ Eq. (227.1)

Obs.: veja comentário pg. 228.1 !

↳

· Movimento partícula carregada sob campos EM estáticos,

vimos que, eqs. de movimento partícula massa m e carga q sob campo EM, Eq. (223.2):

$$\frac{d\vec{p}}{dt} = q \left(\vec{E} + \frac{1}{c} \vec{v} \times \vec{B} \right) \quad ; \quad \vec{p} = \gamma m \vec{v}$$

(228.2)

$$\frac{d\mathcal{E}}{dt} = q \vec{v} \cdot \vec{E} \quad ; \quad \mathcal{E} = \gamma mc^2$$

vamos considerar 4 casos particulares,

$$(1) \quad \vec{E} = \text{cte} \quad \text{e} \quad \vec{B} = 0$$

hipótese $\vec{E} = E \hat{x}$

↳ eqs. de movimento
(228.2)

$$\frac{d\vec{p}}{dt} = q E \hat{x}$$

(228.3)

Obs: o procedimento utilizado acima (descrito nas Sec. 12.1.A, Jackson e §16 Landau) para determinar a Lagrangiana (225.3) não é único; nesse caso, a ideia foi preservar a eq. de Lagrange (223.4);

pl procedimentos alternativos, que consideram o vínculo $U_\mu U^\mu = c^2$, veja Sec. 12.1.B, Jackson e Sec. 2.2, Barut

$$\hookrightarrow \dot{p}_x = \frac{d}{dt} (\gamma m v_x) = qE$$

(229.1)

$$\dot{p}_y = \frac{d}{dt} (\gamma m v_y) = 0 \quad \text{e} \quad \dot{p}_z = \frac{d}{dt} (\gamma m v_z) = 0$$

notas Eqs. (229.1): movimento partícula @ plano

\hookrightarrow hipótese: condição inicial $\vec{v}_0 = v_{0x} \hat{x} + v_{0y} \hat{y}$

\hookrightarrow movimento @ plano xy!

temos que: $\gamma m v_x = qEt + C_1$

$$\gamma m v_y = C_2$$

$$\gamma m v_z = C_3$$

c.i.: $\gamma_0 m v_{0x} = C_1$; $\gamma_0 m v_{0y} = C_2$; $C_3 = 0$

$$\text{onde } \gamma_0 = \left(1 - \frac{v_0^2}{c^2}\right)^{-1/2}$$

$$\hookrightarrow \gamma v_x = \frac{qEt}{m} + \gamma_0 v_{0x} \equiv at + \gamma_0 v_{0x}$$

(229.2)

$$\gamma v_y = \gamma_0 v_{0y} \quad \text{e} \quad v_z = 0$$

próximas etapas: determinar γ ,

notas:

$$\gamma^2 (v_x^2 + v_y^2) = a^2 t^2 + 2a \gamma_0 v_{0x} t + \gamma_0^2 (v_{0x}^2 + v_{0y}^2)$$

$$+1/c^2: \gamma^2 \beta^2 = \gamma^2 - 1 = \frac{a^2 t^2}{c^2} + \frac{2a \gamma_0 v_{0x} t}{c^2} + \gamma_0^2 - 1$$

$$\hookrightarrow \gamma = \frac{1}{c} \left((at)^2 + 2at \gamma_0 v_{0x} + c^2 \gamma_0^2 \right)^{1/2} \quad (229.3)$$

Eqs. (229.2) e (229.3):

$$\frac{v_x}{c} = \frac{at + v_0 v_{0x}}{(a^2 t^2 + 2at v_0 v_{0x} + c^2 v_0^2)^{1/2}}$$

(230.1)

$$\frac{v_y}{c} = \frac{v_0 v_{0y}}{(a^2 t^2 + 2at v_0 v_{0x} + c^2 v_0^2)^{1/2}}$$

como $v_x = \frac{dx}{dt}$ e $v_y = \frac{dy}{dt}$, verifica-se que (exercício):

$$x(t) = \frac{c}{a} (a^2 t^2 + 2at v_0 v_{0x} + c^2 v_0^2)^{1/2} + C_0$$

(230.2)

$$y(t) = \frac{c}{a} v_0 v_{0y} \sinh^{-1} \left(\frac{at + v_0 v_{0x}}{v_0 (c^2 - v_{0x}^2)^{1/2}} \right) + C_1 ; a = qE/m$$

onde ctes C_0 e $C_1 \sim c.i.$

Eq. (230.2): eq. paramétrica trajetória partícula.

definindo: $\bar{x} = x - C_0$ e $\bar{y} = y - C_1$, verifica-se que (230.2) pode ser escrita como (exercício):

$$\bar{x} = \frac{c v_0 m}{qE} (c^2 - v_{0x}^2)^{1/2} \cosh \left(\frac{qE \bar{y}}{m c v_0 v_{0y}} \right) : \text{Eq. catenária!} \quad (230.3)$$

notas:

(i) Eq. (230.1): $t \rightarrow +\infty \Rightarrow v_x \rightarrow c$ e $v_y \rightarrow 0$;

(ii) Eq. (230.3), limite $v \ll c$:

$$\bar{x} \approx \frac{c^2 m}{qE} \cosh \left(\frac{qE \bar{y}}{m c v_{0y}} \right) \approx \frac{c^2 m}{qE} \left(1 + \frac{1}{2} \left(\frac{qE \bar{y}}{m c v_{0y}} \right)^2 \right)$$

$\hookrightarrow \bar{x} \approx \frac{qE}{m v_{0y}^2} \bar{y}^2 + cte : \text{parábola!}$

(2) $\vec{E} = 0$ e $\vec{B} = cte$

Eqs. de movimento (228.2) : $\frac{d\vec{p}}{dt} = \frac{1}{c} q \vec{v} \times \vec{B}$

$\frac{dE}{dt} = \frac{d}{dt} (\gamma mc^2) = 0 \rightarrow v = |\vec{v}| = cte :$

temos que :

$\frac{d\vec{p}}{dt} = \frac{d}{dt} (\gamma m \vec{v}) = \gamma m \frac{d\vec{v}}{dt} = \frac{1}{c} q \vec{v} \times \vec{B}$

$\hookrightarrow \frac{d\vec{v}}{dt} = \vec{v} \times \left(\frac{q\vec{B}}{\gamma mc} \right) = \vec{v} \times \vec{\omega}_B : \text{similar problema (231.1)}$
nã-relativístico,
ponem frequência ciclotrônica
 $\omega_c = qB/mc \rightarrow \omega_B !$

notan : $\vec{\omega}_B = \frac{q\vec{B}}{\gamma mc} = \frac{qc}{E} \vec{B}$

hipótese : $\vec{B} = B \hat{z}$ e c.i. : $\vec{r}(t=0) = (x_0, y_0, z_0)$
 $\vec{v}(t=0) = (v_{0x}, v_{0y}, v_{0z})$

Eq. (231.3) : $\begin{cases} \dot{v}_x = \omega_B v_y \\ \dot{v}_y = -\omega_B v_x \end{cases} \left. \begin{array}{l} \\ \end{array} \right\} \begin{array}{l} 2 \text{ eq. diferenciais} \\ \text{acopladas} \end{array}$
 $\dot{v}_z = 0$

· direção \hat{z} :

$$\dot{v}_z = 0 \rightarrow v_z = C_0 = \frac{dz}{dt} \rightarrow z = C_0 t + C_1$$

$$\text{c.i. : } z(0) = z_0 \rightarrow C_0 = v_{0z} \rightarrow z(t) = v_{0z} t + z_0 :$$

$$v_z(0) = v_{0z} \quad C_1 = z_0 \quad \text{movimento uniforme!}$$

(232.1)

direções \hat{x} e \hat{y}

$$\hookrightarrow \dot{v}_x + i\dot{v}_y = -i\omega_B (v_x + i v_y)$$

$$\hookrightarrow v_x + i v_y = A e^{-i(\omega_B t + \delta)} ; A \in \mathbb{R}$$

$$\text{ou } v_x(t) = A \cos(\omega_B t + \delta)$$

$$v_y(t) = -A \sin(\omega_B t + \delta)$$

$$\text{c.i. : } v_x(0) = v_{0x} = A \cos \delta$$

$$v_y(0) = v_{0y} = -A \sin \delta$$

$$\text{como : } v_x = A \cos \delta \cos \omega_B t - A \sin \delta \sin \omega_B t$$

$$v_y = -A \cos \delta \sin \omega_B t - A \sin \delta \cos \omega_B t$$

$$\hookrightarrow v_x(t) = v_{0x} \cos \omega_B t + v_{0y} \sin \omega_B t$$

(232.2)

$$v_y(t) = -v_{0x} \sin \omega_B t + v_{0y} \cos \omega_B t$$

como :

$$v_x = \frac{dx}{dt} \rightarrow x = \frac{v_{0x}}{\omega_B} \sin \omega_B t - \frac{v_{0y}}{\omega_B} \cos \omega_B t + C_1$$

$$v_y = \frac{dy}{dt} \rightarrow y = \frac{v_{0x}}{\omega_B} \cos \omega_B t + \frac{v_{0y}}{\omega_B} \sin \omega_B t + C_2$$

$$\text{c.i. : } x(0) = x_0 = -v_{0y}/\omega_B + C_1 \rightarrow C_1 = x_0 + v_{0y}/\omega_B$$

$$y(0) = y_0 = v_{0x}/\omega_B + C_2 \rightarrow C_2 = y_0 - v_{0x}/\omega_B$$

Dessa forma,

$$x(t) - (x_0 + v_{0y}/\omega_B) = \frac{v_{0x}}{\omega_B} \sin \omega_B t - \frac{v_{0y}}{\omega_B} \cos \omega_B t$$

$$y(t) - (y_0 - v_{0x}/\omega_B) = \frac{v_{0x}}{\omega_B} \cos \omega_B t + \frac{v_{0y}}{\omega_B} \sin \omega_B t \quad (233.1)$$

$$z(t) - z_0 = v_{0z} t \quad ; \quad \text{equação paramétrica hélice,} \\ \text{eixo} = \hat{z} : \text{direção } \vec{B} !$$

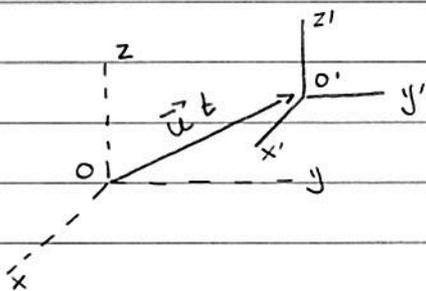
notas : movimento plano xy : movimento circular,

$$\text{raio } a = \frac{1}{\omega_B} (v_{0x}^2 + v_{0y}^2)^{1/2} = \frac{v_{0\perp}}{\omega_B} = \frac{\Gamma m c v_{0\perp}}{q B} = \frac{c p_{0\perp}}{q B}$$

$$(3) \quad \vec{E} = cte, \quad \vec{B} = cte \quad \text{e} \quad \vec{E} \perp \vec{B},$$

ideia : analisar o movimento da partícula REF \mathcal{K}' , escolhido de modo a simplificar eqs. de movimento (228.2)

considerar REFS \mathcal{K} e \mathcal{K}' ,



\vec{u} : velocidade REF \mathcal{K}'
w.r.t. REF \mathcal{K}

eixos $\hat{e}_i \parallel$ eixos \hat{e}'_i

eqs. de movimento (228.2) :

$$\frac{d\vec{p}}{dt} = q \left(\vec{E} + \frac{1}{c} \vec{v} \times \vec{B} \right) \quad ; \quad \vec{E} = cte, \quad \vec{B} = cte, \quad \vec{E} \cdot \vec{B} = 0 \quad ; \quad \text{REF } \mathcal{K}$$

$$\frac{d\vec{p}'}{dt'} = q \left(\vec{E}' + \frac{1}{c} \vec{v}' \times \vec{B}' \right) \quad ; \quad \text{REF } \mathcal{K}'$$

Lembran P 11.14, Jackson:

$$\vec{E} \cdot \vec{B} = -\frac{1}{4} F^{\alpha\beta} \tilde{F}_{\alpha\beta} \quad : \text{escalares, invariantes} \quad (234.1)$$

$$E^2 - B^2 = -\frac{1}{2} F^{\alpha\beta} F_{\alpha\beta} \quad \text{sob transf. de Lorentz}$$

$$\hookrightarrow E^2 - B^2 = E'^2 - B'^2 \quad \text{e} \quad \vec{E} \cdot \vec{B} = \vec{E}' \cdot \vec{B}'$$

notas: (i) se $E' = 0$

$$\hookrightarrow \vec{E} \cdot \vec{B} = \vec{E}' \cdot \vec{B}' = 0 \quad : \text{OK}$$

$$\text{e} \quad E^2 - B^2 = -B'^2 \rightarrow E^2 - B^2 < 0 \quad \text{ou} \quad E < B$$

\hookrightarrow se $E < B \rightarrow$ é possível escolher REF \mathcal{K}' tal que $\vec{E}' = 0$

(ii) se $B' = 0$

$$\hookrightarrow \vec{E} \cdot \vec{B} = \vec{E}' \cdot \vec{B}' = 0 \quad : \text{OK}$$

$$\text{e} \quad E^2 - B^2 = E'^2 \rightarrow E^2 - B^2 > 0 \quad \text{ou} \quad E > B$$

\hookrightarrow se $E > B \rightarrow$ é possível escolher REF \mathcal{K}' tal que $\vec{B}' = 0$

vamos analisar os 2 casos separadamente,

(i) hipótese $E < B$,

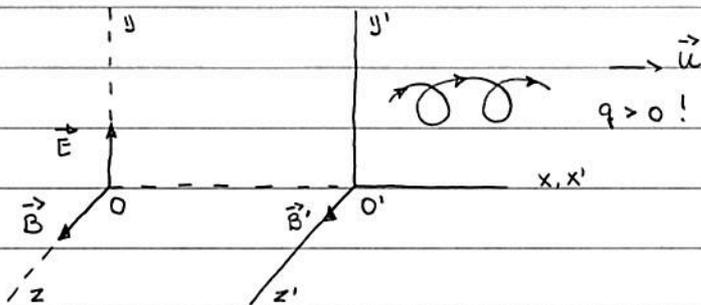
ideia: determinar velocidade \vec{u} REF \mathcal{K}' tal que $\vec{E}' = 0$

Lembran: transf. campos \vec{E} e \vec{B} , Eq. (217.2):

$$\vec{E}' = \gamma (\vec{E} + \vec{\beta} \times \vec{B}) - \frac{\gamma^2}{\gamma+1} \vec{\beta} (\vec{\beta} \cdot \vec{E}) \quad \vec{\beta} = \vec{u}/c$$

$$\vec{B}' = \gamma (\vec{B} - \vec{\beta} \times \vec{E}) - \frac{\gamma^2}{\gamma+1} \vec{\beta} (\vec{\beta} \cdot \vec{B}) \quad \gamma = (1 - u^2/c^2)^{-1/2}$$

hipótese : $\vec{E} = E \hat{y}$, $\vec{B} = B \hat{z} \rightarrow \vec{u} = u \hat{x}$



(ii) hipótese $E > B$,

ideia : determinar velocidade \vec{u} REF K' tal que $\vec{B}' = 0$

de modo análogo ao caso anterior, verifica-se que uma possível escolha é

$$\vec{u} = c \frac{1}{E^2} \vec{E} \times \vec{B} \quad (236.1)$$

notas : $\vec{u} \perp \vec{E}$; $\vec{u} \perp \vec{B}$ e

$$\vec{B}' = \gamma \left(\vec{B} + \frac{1}{E^2} \vec{E} \times (\vec{E} \times \vec{B}) \right) = 0$$

$-E^2 \vec{B}$

$$\vec{E}' = \gamma \left(\vec{E} - \frac{1}{E^2} \vec{B} \times (\vec{E} \times \vec{B}) \right) = \gamma \left(1 - \frac{B^2}{E^2} \right) \vec{E} =$$

$B^2 \vec{E}$

$$= \left(1 - \frac{B^2}{E^2} \right)^{1/2} \vec{E} = \frac{1}{\gamma} \vec{E} \quad (236.2)$$

notas $\vec{E}' \perp \vec{E}$ e $E' < E$!

↳ Eq. de movimento REF K' : $\frac{d\vec{p}'}{dt'} = q \vec{E}' =$ eq. de movimento (228.3) = caso (1)!

(veja P 12.3, Jackson!)

Obs.: veja Sec. 22, Landau p/ discussão sobre o caso
 $E = B$ e $\vec{E} \cdot \vec{B} = 0$.

(4) $\vec{E} = cte$, $\vec{B} = cte$ e $\vec{E} \cdot \vec{B} \neq 0$,

$$\text{Eq. (234.1)} : \vec{E} \cdot \vec{B} = \vec{E}' \cdot \vec{B}' \rightarrow E B \cos \theta = E' B' \cos \theta'$$

notas: se $0 \leq \theta < \pi/2 \rightarrow 0 \leq \theta' < \pi/2$ sinal $\cos \theta$ é
 : invariante sob
 se $\pi/2 < \theta \leq \pi \rightarrow \pi/2 < \theta' \leq \pi$ transf. Lorentz !

vamos verificar que:

- se $0 \leq \theta < \pi/2 \rightarrow$ é possível determinar REF κ'
 tal que $\theta' = 0$ ou $\vec{E}' = \alpha \vec{B}'$, $\alpha > 0$

- se $\pi/2 < \theta \leq \pi \rightarrow$ " " " "
 " $\theta' = \pi$ ou $\vec{E}' = -\alpha \vec{B}'$, $\alpha > 0$

hipótese (i): $\vec{E}' \times \vec{B}' = 0$ e $\vec{u} \cdot \vec{E} = \vec{u} \cdot \vec{B} = 0$

\hookrightarrow transf. campos \vec{E} e \vec{B} (217.2):

$$\vec{E}' = \gamma (\vec{E} + \vec{\beta} \times \vec{B}) \quad \text{e} \quad \vec{B}' = \gamma (\vec{B} - \vec{\beta} \times \vec{E})$$

Verifica-se que (exercício):

$$\begin{aligned} \vec{E}' \times \vec{B}' &= \gamma^2 (\vec{E} + \vec{\beta} \times \vec{B}) \times (\vec{B} - \vec{\beta} \times \vec{E}) \\ &= \gamma^2 (\vec{E} \times \vec{B} - (E^2 + B^2) \vec{\beta} + \vec{\beta} (\vec{\beta} \cdot (\vec{E} \times \vec{B}))) = 0 \end{aligned} \quad \begin{array}{l} \text{escolha!} \\ \downarrow \\ (237.1) \end{array}$$

hipótese (ii) : $\vec{\beta} = \frac{\vec{u}}{c} = \lambda \frac{\vec{E} \times \vec{B}}{EB}$, onde $\lambda = cte$ (238.1)

Eqs. (237.1) e (238.1) :

$$\gamma^2 (\vec{E} \times \vec{B}) \left(1 - \frac{(E^2 + B^2)}{EB} \lambda + \frac{\lambda^2}{(EB)^2} \underbrace{(\vec{E} \times \vec{B}) \cdot (\vec{E} \times \vec{B})}_{E^2 B^2 - (\vec{E} \cdot \vec{B})^2} \right) = 0$$

$$\lambda^2 \sin^2 \theta$$

$\hookrightarrow \lambda^2 EB \sin^2 \theta - (E^2 + B^2) \lambda + EB = 0$: eq. 2^o grau p/ λ !

\exists sol. $\lambda \in \mathbb{R} \rightarrow (E^2 + B^2)^2 - 4(EB)^2 \sin^2 \theta = \Delta > 0$

De fato : $\Delta = E^4 + B^4 + 2E^2 B^2 \underbrace{(1 - 2 \sin^2 \theta)}_{= -1 + 2 \cos^2 \theta = \cos 2\theta}$

$$> E^4 + B^4 - 2E^2 B^2 = (E^2 - B^2)^2 > 0 ! \quad (238.2)$$

Eq. (238.2) : indica que é possível escolher REF \mathcal{K}' tal que velocidade \vec{u} REF \mathcal{K}' w.r.t. REF $\mathcal{K} =$ Eq. (238.1);
nesse caso, REF \mathcal{K}' é tal que $\vec{E}' \perp \vec{B}'$!

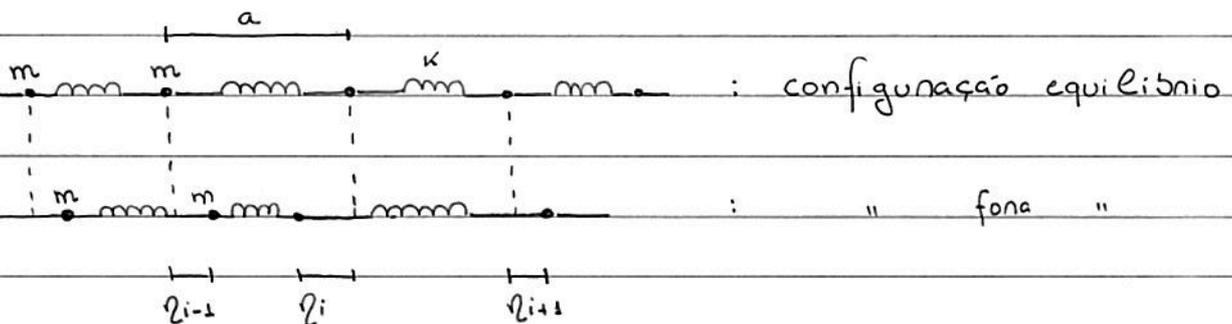
Obs. : p/ trajetória partícula, veja P 12.6, Jackson.

↳ Lagnangiana do campo EM,

ideia: determinar Lagnangiana do sistema campo EM ⊕ fontes

inicial: revisão formalismo Lagnangiano para meios contínuos
(p/ detalhes, veja Sec. 13.2, Goldstein, 3ª ed.)

considerar: sistema 1-D, N partículas massas m conectadas por
molas, cte mola k ; distância entre partículas
equilíbrio = a .



se $q_i = q_i(t)$: deslocamento partícula i w.r.t. posição equilíbrio

$$\hookrightarrow L = T - U = \frac{1}{2} \sum_{i=1}^N m \dot{q}_i^2 - k (q_{i+1} - q_i)^2 \quad : \text{Lagnangiana (239.1)} \\ \text{ sistema discreto}$$

Eq. (239.1) pode ser escrita como

$$L = \frac{1}{2} \sum_{i=1}^N a \left(\frac{m}{a} \dot{q}_i^2 - k a \frac{1}{a^2} (q_{i+1} - q_i)^2 \right) = \sum_{i=1}^N a L_i$$

considerando limite $N \rightarrow +\infty$, $a \rightarrow 0$, verifica-se que

$$L = \sum_{i=1}^N a L_i \rightarrow \int dx \mathcal{L} \quad : \text{Lagnangiana sistema} \\ \text{ contínuo}$$

onde

(239.2)

$$\mathcal{L} = \frac{1}{2} \mu \left(\frac{\partial \eta}{\partial t} \right)^2 - \frac{1}{2} \Upsilon \left(\frac{\partial \eta}{\partial x} \right)^2 \quad : \text{densidade de} \\ \text{ Lagnangiana}$$

nesse caso : $q_i(t) \rightarrow q(x,t)$

$m/a \rightarrow \mu$: densidade de massa

Y : módulo de Young.

notas : $\mathcal{L} = \mathcal{L}(\partial_x q, \partial_t q)$!

caso geral : considerar sistema 1-D (discreto) descrito pelas

coordenadas generalizadas q_1, q_2, \dots, q_n ;

a generalização p/ caso $n \rightarrow +\infty$ pode ser obtida via as identificações :

$i \rightarrow x$ ou $(a_i \rightarrow x)$

$q_i(t) \rightarrow \phi(x,t)$: campo escalar

$\dot{q}_i(t) \rightarrow \partial_t \phi(x,t)$ (240.1)

se $L = \sum_{i=1}^n L_i \rightarrow \int dx \mathcal{L}$

onde (caso geral) $\mathcal{L} = \mathcal{L}(\phi, \partial_x \phi, \partial_t \phi, x, t)$: densidade de Lagrangiana

Além disso, a ação (221.1) assume a forma

$$S = \int_{-\infty}^{+\infty} dx \int_1^2 dt \mathcal{L} \quad (240.2)$$

e o princípio de Hamilton p/ meios contínuos é dado por

$$\delta S = \delta \int dx dt \mathcal{L} = 0 \quad (240.3)$$

próxima etapa : determinar eq. de Lagrange p/ campo escalar $\phi = \phi(x,t)$ a partir (240.3)

ideia : seguir procedimento análogo pg. 221.1.

seja $\phi_0(x,t)$: configuração campo escalar que corresponde extremo ação S ;

considerar variação: $\phi(x,t) = \phi_0(x,t) + \alpha \zeta(x,t)$

$$\text{tal que } \zeta(x \rightarrow \pm\infty, t) = \zeta(x, t = t_1) = \zeta(x, t = t_2) = 0$$

$$L \rightarrow \mathcal{L} = \mathcal{L}(\phi_0 + \alpha \zeta, \partial_x \phi_0 + \alpha \partial_x \zeta, \partial_t \phi_0 + \alpha \partial_t \zeta, x, t)$$

$$L \rightarrow S = S[\alpha]$$

nesse caso, δS pode ser determinado via

$$\frac{dS}{d\alpha} = \int dx dt \left(\underbrace{\frac{\partial \mathcal{L}}{\partial \phi} \frac{\partial \phi}{\partial \alpha}}_{\zeta} + \underbrace{\frac{\partial \mathcal{L}}{\partial(\partial_x \phi)} \frac{\partial(\partial_x \phi)}{\partial \alpha}}_{\partial_x \zeta} + \underbrace{\frac{\partial \mathcal{L}}{\partial(\partial_t \phi)} \frac{\partial(\partial_t \phi)}{\partial \alpha}}_{\partial_t \zeta} \right)$$

$$= \int dx dt \left(-\partial_x \left(\frac{\partial \mathcal{L}}{\partial(\partial_x \phi)} \right) \zeta + \frac{d}{dx} \left(\frac{\partial \mathcal{L}}{\partial(\partial_x \phi)} \zeta \right) \right)$$

$= 0$, pois $\zeta(x \rightarrow \pm\infty, t) = 0$

procedendo de modo análogo p/ o terceiro termo, temos que

$$\frac{dS}{d\alpha} = \int dx dt \left(\frac{\partial \mathcal{L}}{\partial \phi} - \frac{\partial}{\partial x} \left(\frac{\partial \mathcal{L}}{\partial(\partial_x \phi)} \right) - \frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial(\partial_t \phi)} \right) \right) \zeta(x,t)$$

como $\zeta = \zeta(x,t)$ é arbitrário, a condição $dS/d\alpha = 0$

$$L \rightarrow \frac{\partial \mathcal{L}}{\partial \phi} - \frac{\partial}{\partial x} \left(\frac{\partial \mathcal{L}}{\partial(\partial_x \phi)} \right) - \frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial(\partial_t \phi)} \right) = 0 : \quad (241.1)$$

: Eq. de Lagrange

como $\frac{\partial}{\partial x} \equiv \frac{\partial}{\partial t} \rightarrow \frac{\partial}{\partial x^\mu} \equiv$ Eq. (199.4) : $\partial_\mu \equiv \frac{\partial}{\partial x^\mu}$

$$\hookrightarrow \text{Eq. (241.1)} : \frac{\partial \mathcal{L}}{\partial \phi} - \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi)} \right) = 0 \quad (242.1)$$

notas: Eqs. (240.2) e (242.1) podem ser generalizadas
p/ caso sistema descrito campos

$$\phi_i(\vec{r}, t); \quad i = 1, 2, \dots, n :$$

$$S = \int d^3r dt \mathcal{L} = \int d^4x \mathcal{L}$$

$$\text{onde } \mathcal{L} = \mathcal{L}(\phi_i, \partial_\mu \phi_i, x^\mu, t)$$

$$e \quad \frac{\partial \mathcal{L}}{\partial \phi_i} - \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_i)} \right) = 0; \quad i = 1, 2, \dots, n \quad (242.2)$$

$$\mu = 0, 1, 2, 3$$

• caso particular: campo EM,

$$\text{nesse caso: } \phi_i(\vec{r}, t) \rightarrow A^\alpha(\vec{r}, t)$$

$$\partial_\mu \phi_i \rightarrow \partial_\mu A^\alpha$$

$$\text{Lembrar: } d^4x' = \frac{\partial(x'^0, x'^1, x'^2, x'^3)}{\partial(x^0, x^1, x^2, x^3)} d^4x = (\det A) d^4x = d^4x$$

= 1 p/ transf. Lorentz

próprias (veja pg. 202)

como d^4x é invariante sob transf. Lorentz

\hookrightarrow ação S " " " " " se

\mathcal{L} é um escalar!

vamos considerar 2 casos a fim de determinar a
densidade de Lagrangiana,

(i) ausência fontes externas,

nesse caso, a analogia c/ sistema partículas, e.g., Eq. (239.2)

$\hookrightarrow \mathcal{L} \sim$ termo de energia cinética $\sim (\partial_\mu \phi_i)^2 \rightarrow (\partial_\mu A^\nu)^2$

Lembrar: Eq. (211.2) : $F^{\alpha\beta} = \partial^\alpha A^\beta - \partial^\beta A^\alpha$

Eq. (234.1) : $F^{\alpha\beta} \tilde{F}_{\alpha\beta} = -4 \vec{E} \cdot \vec{B}$: invariantes

$F^{\alpha\beta} F_{\alpha\beta} = -2(E^2 - B^2)$ sob transf. Lorentz

entretanto, sob inversão espacial (paridade), temos que

Eq. (74.2) : $\vec{E} \rightarrow -\vec{E}$ e $\vec{B} \rightarrow +\vec{B}$

\hookrightarrow sob inversão $F^{\alpha\beta} \tilde{F}_{\alpha\beta} \rightarrow -F^{\alpha\beta} \tilde{F}_{\alpha\beta}$: pseudoescalar

espacial : $F^{\alpha\beta} F_{\alpha\beta} \rightarrow +F^{\alpha\beta} F_{\alpha\beta}$: escalar

$\hookrightarrow \mathcal{L} \propto F^{\alpha\beta} F_{\alpha\beta}$: escalar sob transf. Lorentz e

" inversão espacial

verifica-se que (veja abaixo) :

$$\mathcal{L} = -\frac{1}{16\pi} F_{\alpha\beta} F^{\alpha\beta} \quad (243.3)$$

(ii) \oplus fontes externas,

nesse caso, $\mathcal{L} \sim J^\alpha = (c\rho, \vec{J})$

vimos que, p/ partícula carregada sob campo EM,

$\mathcal{L} \sim U^\alpha A_\alpha$: Eq. (225.3);

novamente, analogia c/ sistema partículas

$$\hookrightarrow \mathcal{L} \propto J_\alpha A^\alpha$$

verifica-se que (veja abaixo) : $\mathcal{L} = -\frac{1}{c} J_\alpha A^\alpha$ (244.1)

\hookrightarrow Eqs. (243.3) e (244.1) :

$$\mathcal{L} = -\frac{1}{16\pi} F_{\alpha\beta} F^{\alpha\beta} - \frac{1}{c} J_\alpha A^\alpha : \text{densidade de Lagrangiana} \\ \text{campo EM} \quad (244.2)$$

próxima etapa: determinar eqs. de movimento p/ A^α ,

$$\text{como: } F_{\mu\nu} F^{\mu\nu} = g_{\mu\lambda} g_{\nu\sigma} F^{\lambda\sigma} F^{\mu\nu}$$

$$= g_{\mu\lambda} g_{\nu\sigma} (\partial^\lambda A^\sigma - \partial^\sigma A^\lambda)(\partial^\mu A^\nu - \partial^\nu A^\mu)$$

$$\hookrightarrow \mathcal{L} = -\frac{1}{16\pi} g_{\mu\lambda} g_{\nu\sigma} (\partial^\lambda A^\sigma - \partial^\sigma A^\lambda)(\partial^\mu A^\nu - \partial^\nu A^\mu) - \frac{1}{c} J_\mu A^\mu$$

$$\text{Eq. de Lagrange} \quad \frac{\partial \mathcal{L}}{\partial A^\alpha} - \partial^\beta \left(\frac{\partial \mathcal{L}}{\partial (\partial^\beta A^\alpha)} \right) = 0 \quad (244.3)$$

(242.2) :

$$\text{como: } \frac{\partial \mathcal{L}}{\partial A^\alpha} = -\frac{1}{c} J_\alpha$$

$$= \frac{\partial \mathcal{L}}{\partial (\partial^\beta A^\alpha)} = -\frac{1}{16\pi} g_{\mu\lambda} g_{\nu\sigma} \left(\delta_{\beta^\lambda} \delta_{\alpha^\sigma} F^{\mu\nu} - \delta_{\beta^\sigma} \delta_{\alpha^\lambda} F^{\mu\nu} + \right. \\ \left. + \delta_{\beta^\mu} \delta_{\alpha^\nu} F^{\lambda\sigma} - \delta_{\beta^\nu} \delta_{\alpha^\mu} F^{\lambda\sigma} \right)$$

$$= -\frac{1}{16\pi} \left(g_{\mu\beta} g_{\nu\alpha} F^{\mu\nu} - g_{\mu\alpha} g_{\nu\beta} F^{\mu\nu} + g_{\beta\lambda} g_{\alpha\sigma} F^{\lambda\sigma} - g_{\alpha\lambda} g_{\beta\sigma} F^{\lambda\sigma} \right)$$

$$= -\frac{1}{16\pi} (F_{\beta\alpha} - F_{\alpha\beta} + F_{\beta\alpha} - F_{\alpha\beta})$$

$$= -\frac{1}{4\pi} F_{\beta\alpha} = \frac{1}{4\pi} F_{\alpha\beta}$$

(245.1.0)

$$\hookrightarrow \text{Eq. (244.3)} : \frac{1}{4\pi} \partial^\beta F_{\beta\alpha} = \frac{1}{c} J_\alpha : \text{Eq. (213.1)} : (*)$$

forma covariante eqs. de Maxwell
n\u00e3o-hom\u00f4neas!

notas: (*) \rightarrow coeficientes Lagrangiana (244.2) ok!

sobre as equa\u00e7\u00f5es de Maxwell homog\u00eneas: n\u00e3o s\u00e3o derivadas a partir de (244.2); lembrar que eqs. homog\u00eneas est\u00e3o contidas na defini\u00e7\u00e3o $F^{\alpha\beta}$ (veja pg. 211) e podem ser escritas como (forma covariante)

$$\partial_\alpha \tilde{F}^{\alpha\beta} = 0 : \text{Eq. (214.2)} ; \text{notas: 4 equa\u00e7\u00f5es!}$$

ou (veja pg. 245.1):

$$\partial_\alpha F_{\beta\gamma} + \partial_\beta F_{\gamma\alpha} + \partial_\gamma F_{\alpha\beta} = 0 ; \alpha, \beta, \gamma = 0, 1, 2, 3 \quad (245.1)$$

notas: 4-divergente (*)

$$\hookrightarrow \frac{1}{c} \partial^\alpha J_\alpha = \frac{1}{4\pi} \partial^\alpha \partial^\beta F_{\alpha\beta} = \frac{1}{8\pi} (\partial^\alpha \partial^\beta F_{\alpha\beta} + \underbrace{\partial^\alpha \partial^\beta F_{\beta\alpha}}_{= -\partial^\alpha \partial^\beta F_{\alpha\beta}}) = 0$$

$$\partial^\beta \partial^\alpha F_{\beta\alpha} = -\partial^\alpha \partial^\beta F_{\alpha\beta}$$

$\hookrightarrow \partial^\alpha J_\alpha = 0$: forma covariante, eq. de continuidade (209.3)!

• Vamos derivar Eq. (245.1) a partir Eq. (244.2),

$$\partial_\alpha \tilde{F}^{\alpha\beta} = \frac{1}{2} \partial_\alpha (\epsilon^{\alpha\beta\mu\nu} F_{\mu\nu}) = 0$$

$$\text{se } \beta = 0; \quad \partial_\alpha \tilde{F}^{\alpha 0} = \frac{1}{2} \partial_\alpha (\epsilon^{\alpha 0\mu\nu} F_{\mu\nu}) =$$

$$= \frac{1}{2} \left(\partial_1 \tilde{F}_{23} - \underbrace{\partial_1 F_{32}}_{=-F_{23}} + \partial_2 \tilde{F}_{31} - \underbrace{\partial_2 F_{13}}_{=-F_{31}} + \partial_3 \tilde{F}_{12} - \underbrace{\partial_3 F_{21}}_{=-F_{12}} \right)$$

$$= \partial_1 \tilde{F}_{23} + \partial_2 \tilde{F}_{31} + \partial_3 \tilde{F}_{12} = 0$$

análogo p/ $\beta = 1, 2, 3 \rightarrow$ Eq. (245.1) !

• Obs.: densidade de lagrangiana (244.2) pode ser escrita como

$$\mathcal{L} = -\frac{1}{16\pi} g_{\alpha\mu} g_{\beta\nu} (\partial^\alpha A^\beta - \partial^\beta A^\alpha) (\partial^\mu A^\nu - \partial^\nu A^\mu) - \frac{1}{c} \mathbf{J} \cdot \mathbf{A}$$

$$= \frac{1}{8\pi} (E^2 - B^2) - \rho\Phi + \frac{1}{c} \vec{\mathbf{J}} \cdot \vec{\mathbf{A}}$$

$$= \frac{1}{8\pi} \left(\left(-\vec{\nabla}\Phi - \frac{1}{c} \partial_t \vec{\mathbf{A}} \right)^2 - (\vec{\nabla} \times \vec{\mathbf{A}})^2 \right) - \rho\Phi + \frac{1}{c} \vec{\mathbf{J}} \cdot \vec{\mathbf{A}}$$

(245.2)

Ex.: densidades de Lagrangiana e eqs. de movimento
(veja Sec. 3.3, Barut)

(1) Campo escalar real,

$$\mathcal{L} = \frac{1}{2} (g^{\mu\nu} \partial_\mu \phi \partial_\nu \phi - m^2 \phi^2) ; \phi = \phi(\vec{r}, t) \quad (245.3)$$

eq. de Lagrange (242.2),

$$\frac{\partial \mathcal{L}}{\partial \phi} - \partial_\alpha \left(\frac{\partial \mathcal{L}}{\partial (\partial_\alpha \phi)} \right) = 0$$

$$\text{como } \frac{\partial \mathcal{L}}{\partial \phi} = -m^2 \phi \quad \text{e} \quad \frac{\partial \mathcal{L}}{\partial (\partial_\alpha \phi)} = \frac{1}{2} (g^{\alpha\nu} \partial_\nu \phi + g^{\mu\alpha} \partial_\mu \phi)$$

$$\hookrightarrow g^{\alpha\nu} \partial_\alpha \partial_\nu \phi + m^2 \phi = 0 \rightarrow (\partial^\nu \partial_\nu + m^2) \phi = 0 : \quad (245.4)$$

: eq. de Klein-Gordon

verifica-se que (exercício)

$$\pi = \frac{\partial \mathcal{L}}{\partial (\partial_t \phi)} = \frac{1}{c} \frac{\partial \mathcal{L}}{\partial (\partial_0 \phi)} = \frac{1}{c} g^{00} \partial_0 \phi = \frac{1}{c^2} \partial_t \phi :$$

: densidade momento canonicamente
conjugado (253.2)

$$\text{e} \quad \mathcal{H} = \frac{1}{2} (c^2 \pi^2 + (\vec{\nabla} \phi)^2 + m^2 \phi^2) : \text{densidade de Hamiltoniana}$$

(2) Campo de Dirac,

$$\mathcal{L} = i \bar{\psi} \gamma^\mu \partial_\mu \psi + m \bar{\psi} \psi \quad (245.5)$$

onde $\psi^i = (\psi_1 \psi_2 \psi_3 \psi_4)$; $\psi_i = \psi_i(\vec{r}, t)$; $\bar{\psi} = \psi^\dagger \gamma^0$;

$$\gamma^0 = \beta = \begin{pmatrix} \hat{1}_{2 \times 2} & 0 \\ 0 & \hat{1}_{2 \times 2} \end{pmatrix} \quad \gamma^i = \beta \alpha_i = \begin{pmatrix} 0 & \sigma_i \\ \sigma_i & 0 \end{pmatrix}$$

eqs. de Lagrange (242.2),

$$\frac{\partial \mathcal{L}}{\partial \psi_\lambda} - \partial_\nu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\nu \psi_\lambda)} \right) = 0 \quad \text{e} \quad \frac{\partial \mathcal{L}}{\partial \psi_\lambda^\dagger} - \partial_\nu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\nu \psi_\lambda^\dagger)} \right) = 0$$

$$\text{como } \mathcal{L} = i \psi_\alpha^\dagger \gamma_{\alpha\beta}^0 \gamma_{\beta\gamma}^\mu \partial_\mu \psi_\gamma + m \psi_\alpha^\dagger \gamma_{\alpha\beta}^0 \psi_\beta$$

$$\hookrightarrow \frac{\partial \mathcal{L}}{\partial \psi_\lambda^\dagger} = i \gamma_{\lambda\alpha}^0 \gamma_{\alpha\beta}^\mu \partial_\mu \psi_\beta + m \gamma_{\lambda\beta}^0 \psi_\beta$$

$$\frac{\partial \mathcal{L}}{\partial \psi_\lambda} = m \psi_\alpha^\dagger \gamma_{\alpha\lambda}^0 \quad \text{e} \quad \frac{\partial \mathcal{L}}{\partial (\partial_\nu \psi_\lambda)} = i \psi_\alpha^\dagger \gamma_{\alpha\lambda}^0 \gamma_{\lambda\alpha}^\nu$$

$$\hookrightarrow i (\gamma^0 \gamma^\nu \partial_\nu \psi)_\lambda + m (\psi^\dagger)_\lambda = 0 \rightarrow (i \gamma^\nu \partial_\nu + m) \psi = 0$$

$$\hookrightarrow m (\psi^\dagger \gamma^0)_\lambda - i (\partial_\nu \psi^\dagger \gamma^0 \gamma^\nu)_\lambda = 0 \rightarrow i \partial_\nu \bar{\psi} \gamma^\nu - m \bar{\psi} = 0$$

(245.6)

· tensores de tensão canônico e simétrico,

ideia: determinar as leis de conservação de energia (60.4),
momentos linear (63.1) e angular (66.1) no
formalismo Lagrangiano!

hipótese: $\mathcal{L} = \mathcal{L}(\phi_i, \partial_\mu \phi_i)$, i.e.,

\mathcal{L} não depende explicitamente da posição e do tempo
↳ sistema invariante sob translações espacial e
temporal (veja abaixo) → momento linear e
energia total são conservados!

notas:

$$\frac{\partial \mathcal{L}}{\partial x^\nu} = \partial_\nu \mathcal{L} = \frac{\partial \mathcal{L}}{\partial \phi_i} \partial_\nu \phi_i + \frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_i)} \partial_\nu (\partial_\mu \phi_i)$$

notas!

Eq. de Lagrange (242.2) $\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_i)} = \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_i)} \right) (\partial_\nu \phi_i) + \frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_i)} \partial_\mu (\partial_\nu \phi_i)$

$$= \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_i)} (\partial_\nu \phi_i) \right) = \partial_\nu \mathcal{L} = \delta_{\nu}^{\mu} \partial_\mu \mathcal{L}$$

$$\hookrightarrow \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_i)} (\partial_\nu \phi_i) - \delta_{\nu}^{\mu} \mathcal{L} \right) = 0 \tag{246.1}$$

$$\underbrace{\hspace{10em}}_{= T^{\mu}_{\nu}}$$

como $T^{\alpha\beta} = g^{\beta\nu} T^{\alpha}_{\nu} = g^{\beta\nu} \frac{\partial \mathcal{L}}{\partial (\partial_\alpha \phi_i)} (\partial_\nu \phi_i) - g^{\beta\nu} \delta_{\nu}^{\mu} \mathcal{L}$

$$\hookrightarrow T^{\alpha\beta} = \frac{\partial \mathcal{L}}{\partial(\partial_\alpha \phi_i)} (\partial^\beta \phi_i) - g^{\alpha\beta} \mathcal{L} \quad : \text{tensor de} \quad (247.1)$$

tensão canônico

notar: Eq. (246.1) $\rightarrow T^{\alpha\beta}$ satisfaz uma lei de conservação, pois

$$\partial_\alpha T^{\alpha\beta} = 0 \quad (247.2)$$

ou, em forma integral,

$$\int_V d^3n \partial_0 T^{0\beta} = \frac{1}{c} \frac{d}{dt} \int_V d^3n T^{0\beta} = - \int_V d^3n \partial_i T^{i\beta} \stackrel{\text{Eq. (64.2)}}{=} - \oint_S T^{i\beta} (n_i ds)$$

$$\hookrightarrow \frac{1}{c} \frac{d}{dt} \int_V d^3n T^{0\beta} = - \oint_S T^{i\beta} (n_i ds) \quad : \text{comparar} \quad (247.3)$$

Eq. (64.2)!

próxima etapa: considerar $T^{\alpha\beta}$ p/ caso EM;
discussão em duas etapas.

(i) ausência de fontes

$$\text{nesse caso: } \mathcal{L} = -\frac{1}{16\pi} F_{\alpha\beta} F^{\alpha\beta} \quad : \text{Eq. (243.3)}$$

$$\stackrel{e}{=} T^{\alpha\beta} = \frac{\partial \mathcal{L}}{\partial(\partial_\alpha A^\lambda)} (\partial^\beta A^\lambda) - g^{\alpha\beta} \mathcal{L}$$

$$= g^{\alpha\mu} \frac{\partial \mathcal{L}}{\partial(\partial_\mu A^\lambda)} (\partial^\beta A^\lambda) - g^{\alpha\beta} \mathcal{L}$$

$$\text{Eq. (245.1.0)} \quad \underbrace{\quad \quad \quad}_{\stackrel{*}{=} -\frac{1}{4\pi} F_{\mu\lambda}}$$

$$= -\frac{1}{4\pi} g^{\alpha\mu} F_{\mu\lambda} (\partial^\beta A^\lambda) - g^{\alpha\beta} \mathcal{L} \quad (247.4)$$

verifica-se que (veja, e.g., Eqs. (12.105), Jackson) que tensor $T^{\alpha\beta}$ definido em (247.4) não é simétrico ou antisimétrico w.r.t. $\alpha \leftrightarrow \beta$!

↳ próxima etapa: definir tensor simétrico w.r.t. $\alpha \leftrightarrow \beta$ a partir de $T^{\alpha\beta}$ e que preserve a lei de conservação (247.2).

Obs.: $T^{\alpha\beta} \neq$ tensor de tensão de Maxwell $T_{ij}^{(M)}$ definido em (64.1)!

como $F^{\beta\lambda} = \partial^\beta A^\lambda - \partial^\lambda A^\beta$, temos que

$$\begin{aligned} T^{\alpha\beta} &= -\frac{1}{4\pi} g^{\alpha\mu} F_{\mu\lambda} \underbrace{(F^{\beta\lambda} + \partial^\lambda A^\beta)}_{= -F^{\lambda\beta}} + \frac{1}{16\pi} g^{\alpha\beta} F_{\mu\nu} F^{\mu\nu} \\ &= \frac{1}{4\pi} \underbrace{(g^{\alpha\mu} F_{\mu\lambda} F^{\lambda\beta} + \frac{1}{4} g^{\alpha\beta} F_{\mu\nu} F^{\mu\nu})}_{\equiv \Theta^{\alpha\beta}} - \frac{1}{4\pi} \underbrace{g^{\alpha\mu} F_{\mu\lambda} (\partial^\lambda A^\beta)}_{\equiv T_D^{\alpha\beta}} \end{aligned}$$

verifica-se que (veja pg. 248.1) $\Theta^{\alpha\beta}$ é simétrico w.r.t. $\alpha \leftrightarrow \beta$ e invariante sob transf. de gauge.

sobre o termo $T_D^{\alpha\beta}$,

$$T_D^{\alpha\beta} = -\frac{1}{4\pi} F^\alpha{}_\lambda (\partial^\lambda A^\beta) = -\frac{1}{4\pi} F^\alpha{}_\lambda g^{\lambda\mu} (\partial_\mu A^\beta) = +\frac{1}{4\pi} F^{\mu\alpha} (\partial_\mu A^\beta)$$

ausência como eq. de Maxwell (213.4): $\frac{1}{4\pi} \partial_\mu F^{\mu\alpha} = \frac{1}{c} J^\alpha = 0$: fontes

$$\text{↳ } T_D^{\alpha\beta} = \frac{1}{4\pi} (F^{\mu\alpha} (\partial_\mu A^\beta) + (\partial_\mu F^{\mu\alpha}) A^\beta) = \frac{1}{4\pi} \partial_\mu (F^{\mu\alpha} A^\beta)$$

• propiedades tensor $\theta^{\alpha\beta}$,

• notan : $g^{\beta\mu} F_{\mu\lambda} F^{\lambda\alpha} = g^{\beta\mu} F_{\mu\lambda} g^{\lambda\bar{\lambda}} g^{\alpha\bar{\mu}} F_{\bar{\lambda}\bar{\mu}}$

$$= g^{\alpha\bar{\mu}} g^{\beta\mu} g^{\lambda\bar{\lambda}} F_{\mu\lambda} F_{\bar{\lambda}\bar{\mu}} = g^{\alpha\bar{\mu}} F^{\beta\bar{\lambda}} F_{\bar{\lambda}\bar{\mu}}$$

$$= g^{\alpha\bar{\mu}} F_{\bar{\mu}\bar{\lambda}} F^{\bar{\lambda}\beta} : \text{simétrico w.r.t. } \alpha \leftrightarrow \beta$$

• Lembrar transf. de gauge (51.3) :

$$\Phi' = \Phi - \frac{1}{c} \partial_t \psi$$

$$\rightarrow A'^{\alpha} = A^{\alpha} - \partial^{\alpha} \psi : \text{forma covariante}$$

$$\vec{A}' = \vec{A} + \vec{\nabla} \psi$$

$$\hookrightarrow F'^{\alpha\beta} = \partial^{\alpha} A'^{\beta} - \partial^{\beta} A'^{\alpha} = \partial^{\alpha} (A^{\beta} - \partial^{\beta} \psi) - \partial^{\beta} (A^{\alpha} - \partial^{\alpha} \psi)$$

$$= F^{\alpha\beta} : \text{tensor } F^{\alpha\beta} \text{ invariante sob transf. gauge}$$

$$\hookrightarrow \text{'' } \theta^{\alpha\beta} \text{ '' '' '' '' '' '' '' !}$$

$$\hookrightarrow \partial_\alpha T_D^{\alpha\beta} = \frac{1}{4\pi} \partial_\alpha \partial_\mu (F^{\mu\alpha} A^\beta) = \frac{1}{8\pi} \left(\partial_\alpha \partial_\mu (F^{\mu\alpha} A^\beta) + \partial_\alpha \partial_\mu (F^{\mu\alpha} A^\beta) \right)$$

$$\alpha \leftrightarrow \mu : \partial_\mu \partial_\alpha (F^{\mu\alpha} A^\beta) = -F^{\mu\alpha}$$

$$\hookrightarrow \partial_\alpha T_D^{\alpha\beta} = 0$$

$$\hookrightarrow \partial_\alpha \Theta^{\alpha\beta} = \partial_\alpha (T^{\alpha\beta} - T_D^{\alpha\beta}) = 0, \text{ i.e., } \Theta^{\alpha\beta} \text{ é simétrico w.r.t. } \alpha \leftrightarrow \beta$$

≡ preserva Lei de conservação
(247.2) ! (249.1)

definição:

$$\Theta^{\alpha\beta} = \frac{1}{4\pi} \left(g^{\alpha\mu} F_{\mu\lambda} F^{\lambda\beta} + \frac{1}{4} g^{\alpha\beta} F_{\mu\nu} F^{\mu\nu} \right) : \text{ tensor de tensão simétrica (249.2)}$$

verifica-se que (veja pg. 249.1):

$$\Theta^{00} = \frac{1}{8\pi} (E^2 + B^2) = u$$

$$\Theta^{0i} = \frac{1}{4\pi} (\vec{E} \times \vec{B})_i = \frac{1}{c} \cdot \frac{c}{4\pi} (\vec{E} \times \vec{B})_i = \frac{1}{c} S_i = c g_i$$

(249.3)

$$\Theta^{ij} = -\frac{1}{4\pi} \left(E_i E_j + B_i B_j - \frac{1}{2} \delta_{ij} (E^2 + B^2) \right) = -T_{ij}^{(M)}$$

$$\text{ou } \Theta^{\alpha\beta} = \begin{pmatrix} u & | & c \vec{g} \\ \hline c \vec{g} & | & -T_{ij}^{(M)} \end{pmatrix}$$

notar Eq. (249.3): expressões no sistema Gaussiano p/ densidade de energia u , vetor de Poynting \vec{S} e tensor de tensão de Maxwell $T_{ij}^{(M)}$!

$$\text{Eqs. (247.3) e (249.1): } \frac{1}{c} \frac{d}{dt} \int_V d^3n \Theta^{0\beta} = - \oint_S \Theta^{i\beta} (n_i dA)$$

• vamos verificar Eqs. (249.3),

$$\text{Eq. (234.1)} : F_{\mu\nu} F^{\mu\nu} = -2(E^2 - B^2)$$

$$\cdot \theta^{00} = \frac{1}{4\pi} \left(\underbrace{g^{0\mu} F_{\mu\lambda} F^{\lambda 0}}_{F_{0\lambda} F^{\lambda 0} = E^2} - \frac{1}{2} (E^2 - B^2) \right) = \frac{1}{8\pi} (E^2 + B^2)$$

$$\cdot \theta^{0i} = \frac{1}{4\pi} g^{0\mu} F_{\mu\lambda} F^{\lambda i} = \frac{1}{4\pi} F_{0\lambda} F^{\lambda i}$$

$$i=1 : \theta^{01} = \frac{1}{4\pi} (E_y B_z - E_z B_y) = \frac{1}{4\pi} (\vec{E} \times \vec{B})_1$$

similar : $i=2 \text{ e } 3$.

$$\cdot \theta^{ij} = \frac{1}{4\pi} \left(\underbrace{g^{i\mu} F_{\mu\lambda} F^{\lambda j}}_{g^{ii} F_{i\lambda} F^{\lambda j}} + \frac{1}{4} \underbrace{g^{ij} (E^2 - B^2)}_{-\frac{1}{4} \delta_{ij}} \right)$$

$$= - F_{i\lambda} F^{\lambda j}$$

$$\text{Como (exercício)} : F_{i\lambda} F^{\lambda j} = E_i E_j + B_i B_j - \delta_{ij} B^2$$

$$\hookrightarrow \theta^{ij} = - T_{ij}^{(M)}$$

$$\begin{aligned}
 \hookrightarrow \beta=0 : \frac{1}{c} \frac{d}{dt} \int d^3n \theta^{00} &= \frac{1}{c} \frac{d}{dt} \int d^3n u = \frac{1}{c} \frac{d}{dt} E_{EM} = \\
 &= - \oint_S \theta^{i0} (n_i dA) = - \frac{1}{c} \oint_S \vec{S} \cdot d\vec{A} : \text{Eq. (61.3) na ausência fontes!}
 \end{aligned}$$

$$\begin{aligned}
 \beta=j : \frac{1}{c} \frac{d}{dt} \int d^3n \theta^{0j} &= \frac{d}{dt} \int d^3n g_j = \frac{dP_{EMj}}{dt} = \\
 &= - \oint_S \theta^{ij} (n_i dA) = \oint_S T_{ij}^{(M)} (n_i dA) = \oint_S T_{ji}^{(M)} (n_i dA) : \\
 &: \text{Eq. (64.2) na ausência de fontes!}
 \end{aligned}$$

· sobre a conservação do momento angular,

$$\text{Eq. (66.2) : } \vec{M} = \vec{T}^{(M)} \times \vec{r} \quad \text{ou} \quad M_{ij} = T_{ik} r_l \epsilon_{jkl}$$

$$\text{temos que : } M_{ij} = T_{ik} r_l \epsilon_{jkl} - T_{il} r_k \epsilon_{jkl}, \quad j \neq l \neq k$$

↳ momento angular campo EM pode ser escrito como tensor ordem 3 (veja P 6.10, Jackson)

$$M_{ijk} = T_{ij} r_k - T_{ik} r_j \tag{250.1}$$

verifica-se que (veja P 12.19, Jackson), a conservação do momento angular pode ser escrita em termos tensor

$$M^{\alpha\beta\gamma} = \theta^{\alpha\beta} x^\gamma - \theta^{\alpha\gamma} x^\beta \tag{250.2}$$

$$\text{notar: } \partial_\alpha M^{\alpha\beta\gamma} = \underbrace{(\partial_\alpha \theta^{\alpha\beta}) x^\gamma}_{=0} + \theta^{\alpha\beta} \underbrace{\partial_\alpha x^\gamma}_{=\delta^\gamma_\alpha} -$$

$$- \underbrace{(\partial_\alpha \theta^{\alpha\gamma}) x^\beta}_{=0} - \theta^{\alpha\gamma} \underbrace{\partial_\alpha x^\beta}_{=\delta^\beta_\alpha} = \theta^{\gamma\beta} - \theta^{\beta\gamma} = 0 \tag{250.3}$$

(iii) \oplus fontes externas,

nesse caso, temos que (caso geral) $\partial_\alpha \theta^{\alpha\beta} \neq 0$

notas:

$$\partial_\alpha \theta^{\alpha\beta} = \frac{1}{4\pi} \left(\underbrace{g^{\alpha\mu} \partial_\alpha (F_{\mu\lambda} F^{\lambda\beta})}_{\partial^\mu} + \frac{1}{4} \underbrace{g^{\alpha\beta} \partial_\alpha (F_{\mu\nu} F^{\mu\nu})}_{\partial^\beta} \right)$$

$$= \frac{1}{4\pi} \left(\underbrace{(\partial^\mu F_{\mu\lambda}) F^{\lambda\beta}}_{\substack{= \frac{4\pi}{c} J_\lambda \\ \text{Eq. de Maxwell} \\ (213.4)}} + \underbrace{F_{\mu\lambda} \partial^\mu F^{\lambda\beta}}_{F_{\mu\nu} \partial^\mu F^{\nu\beta}} + \frac{1}{4} \underbrace{(\partial^\beta F_{\mu\nu}) F^{\mu\nu}}_{\frac{1}{2} F_{\mu\nu} \partial^\beta F^{\mu\nu}} + \frac{1}{4} F_{\mu\nu} \partial^\beta F^{\mu\nu} \right)$$

Eq. de Maxwell
(213.4)

$$\hookrightarrow \partial_\alpha \theta^{\alpha\beta} + \frac{1}{c} F^{\beta\lambda} J_\lambda = \frac{1}{8\pi} F_{\mu\nu} \left(\partial^\mu F^{\nu\beta} + \partial^\mu F^{\beta\nu} + \partial^\beta F^{\mu\nu} \right)$$

Eq. de Maxwell (245.1)

$$= \frac{1}{8\pi} F_{\mu\nu} \left(\partial^\mu F^{\nu\beta} + \partial^\nu F^{\mu\beta} \right) = 0$$

simétrico w.r.t. $\mu \leftrightarrow \nu$;
antisimétrico " "

$$\hookrightarrow \partial_\alpha \theta^{\alpha\beta} + \frac{1}{c} F^{\beta\lambda} J_\lambda = 0 \quad (251.1)$$

notas: $\beta = 0$: $\partial_\alpha \theta^{\alpha 0} + \frac{1}{c} F^{0\lambda} J_\lambda = 0$

$$\partial_0 \theta^{00} + \partial_i \theta^{i0} + \frac{1}{c} F^{0i} J_i = 0$$

$$\hookrightarrow \frac{1}{c} \partial_t u + \frac{1}{c} \vec{\nabla} \cdot \vec{S} + \frac{1}{c} (-\vec{E}) \cdot (-\vec{J}) = 0 \quad : \text{Eq. (60.4)}$$

$$\beta = i : \quad \partial_0 \theta^{0i} + \partial_j \theta^{ji} + \frac{1}{c} F^{i\lambda} J_\lambda = 0$$

$$\frac{1}{c} \partial_t (c g_i) - \partial_j T_{ij}^{(M)} + \underbrace{\frac{1}{c} F^{i0} J_0 + \frac{1}{c} F^{ij} J_j}_{\frac{1}{c} E_i (c p)} = 0$$

notas: $F^{ij} J_j = F^{12} J_2 + F^{13} J_3 = (-B_z)(-J_y) + (B_y)(-J_z) = (\vec{J} \times \vec{B})_i$

$$\hookrightarrow \partial_t g_i + p E_i + \frac{1}{c} (\vec{J} \times \vec{B})_i = \partial_j T_{ij}^{(M)}$$

ou, em forma integral,

$$\frac{d}{dt} \int_V d^3n \vec{g} + \underbrace{\int_V d^3n (p \vec{E} + \frac{1}{c} \vec{J} \times \vec{B})}_{d\vec{P}_{MEC}/dt} = \int_V d^3n \vec{\nabla} \cdot \vec{T} \quad : \text{Eq. (63.4)}$$

• Hamiltoniana do campo EM,

inicial: revisão formalismo Hamiltoniano pr meios contínuos
(pr detalhes, veja Secs. 13.4, Goldstein, 3ª ed.)

considerar: sistema discreto 1-D, N-partículas massas m
⊕ molas, pg. 239

$$\text{Eq. (222.2)} : \quad p_i = \frac{\partial L}{\partial \dot{q}_i} \quad \rightarrow \quad \pi_i = \frac{\partial L}{\partial \dot{\eta}_i} = a \frac{\partial L_i}{\partial \dot{\eta}_i} \quad : \text{momento} \quad (252.1)$$

canonicamente conjugado à $\eta_i = \eta_i(t)$

Eq. (222.3) : $H = \dot{q}_i p_i - L$

$$\hookrightarrow H = \dot{q}_i \pi_i - L = a \frac{\partial L_i}{\partial \dot{q}_i} \dot{q}_i - a \sum_i L_i =$$

$$= \sum_i a \left(\dot{q}_i \frac{\partial L_i}{\partial \dot{q}_i} - L_i \right) \xrightarrow{a \rightarrow 0} H = \int dx \underbrace{\left(\dot{q} \frac{\partial \mathcal{L}}{\partial \dot{q}} - \mathcal{L} \right)}_{\equiv \mathcal{H}} \quad (253.1)$$

temos que,

$$\pi_i = \frac{\partial \mathcal{L}}{\partial \dot{q}_i} : \text{densidade momento canonicamente conjugado a } q = q(x, t)$$

$$\equiv \quad (253.2)$$

$$\mathcal{H} = \pi \dot{q} - \mathcal{L} : \text{densidade de Hamiltoniana}$$

Eqs. (253.2) podem ser generalizadas p/ caso sistema descrito campos $\phi_i = \phi_i(\vec{r}, t)$:

$$\pi^i = \frac{\partial \mathcal{L}}{\partial \dot{\phi}_i} \quad \equiv \quad \mathcal{H} = \pi^i \dot{\phi}_i - \mathcal{L} \quad (253.3)$$

\equiv , verifica-se que, as eqs. de movimento, equivalentes eqs. (222.4), são dadas por

$$\frac{\partial \mathcal{H}}{\partial \pi^i} = \dot{\phi}_i \quad \equiv \quad \frac{\partial \mathcal{H}}{\partial \phi_i} - \frac{d}{dx^j} \left(\frac{\partial \mathcal{H}}{\partial (\partial_j \phi_i)} \right) = -\ddot{\pi}^i \quad (253.4)$$

• caso particular: campo EM,

$$\text{novamente} \quad : \quad \phi_i(\vec{r}, t) \rightarrow A^\alpha(\vec{r}, t)$$

$$(\text{veja pg. 242}) \quad \partial_j \phi_i \rightarrow \partial_\mu A^\alpha$$

temos que,

$$\pi_\mu = \frac{\partial \mathcal{L}}{\partial(\partial_t A^\mu)} = \frac{1}{c} \frac{\partial \mathcal{L}}{\partial(\partial^0 A^\mu)} \quad (254.1)$$

$$\mathcal{H} = \pi_\mu \partial_t A^\mu - \mathcal{L} = c \pi_\mu \partial^0 A^\mu - \mathcal{L} \quad (254.2)$$

$$\epsilon \frac{\partial \mathcal{H}}{\partial \pi_\mu} = \partial_t A^\mu \quad \frac{\partial \mathcal{H}}{\partial A^\mu} - \partial_j \left(\frac{\partial \mathcal{H}}{\partial(\partial_j A^\mu)} \right) = -\partial_t \pi_\mu$$

(254.3)

• momentos canonicamente conjugados:

$$\mu = 0 \quad \pi_0 = \frac{1}{c} \frac{\partial \mathcal{L}}{\partial(\partial^0 A^0)} = 0$$

$$\mu = i \quad \pi_\mu = \frac{1}{c} \frac{\partial \mathcal{L}}{\partial(\partial^0 A^\mu)} = -\frac{1}{4\pi c} F_{0\mu}$$

$$\text{como } F_{0\mu} = g_{0\alpha} g_{\mu\beta} F^{\alpha\beta} = g_{\mu\beta} F^{0\beta} = -F^{0\mu} = -(\partial^0 A^\mu - \partial^\mu A^0)$$

$$= \partial^\mu A^0 - \partial^0 A^\mu = -\partial_i \Phi - \frac{1}{c} \partial_t A_i$$

$$\hookrightarrow \pi_\mu = -\pi_i = -\frac{1}{4\pi c} \left(-\partial_i \Phi - \frac{1}{c} \partial_t A_i \right)$$

$$\hookrightarrow \vec{\pi} = -\frac{1}{4\pi c} \left(\vec{\nabla} \Phi + \frac{1}{c} \partial_t \vec{A} \right) \quad (254.4)$$

• Hamiltoniana:

Eqs. (245.2) e (254.2),

$$\mathcal{H} = \underbrace{\pi_0 \partial_t \Phi}_{=0} - \pi_i \partial_t A_i - \mathcal{L}$$

↑
notan since!

$$\mathcal{H} = -\pi_i \partial_t A_i - \frac{1}{8\pi} \left((-\vec{\nabla}\Phi - \frac{1}{c} \partial_t \vec{A})^2 - (\vec{\nabla} \times \vec{A})^2 \right) + \rho\Phi - \frac{1}{c} \vec{J} \cdot \vec{A}$$

como $\partial_t A_i = -4\pi c^2 \pi_i - c \partial_i \Phi$

$$\hookrightarrow \mathcal{H} = \pi_i \left(4\pi c^2 \pi_i + c \partial_i \Phi \right) - 2\pi c^2 \vec{\pi}^2 + \frac{1}{8\pi} (\vec{\nabla} \times \vec{A})^2 + \rho\Phi - \frac{1}{c} \vec{J} \cdot \vec{A}$$

$$\hookrightarrow \mathcal{H} = 2\pi c^2 \vec{\pi}^2 + \frac{1}{8\pi} (\vec{\nabla} \times \vec{A})^2 + c \vec{\pi} \cdot \vec{\nabla} \Phi + \rho\Phi - \frac{1}{c} \vec{J} \cdot \vec{A} \quad (255.1)$$

: densidade de Hamiltoniana campo EM!

notar: $\mathcal{H} = \mathcal{H}(\pi_i, A^\mu, \partial_j A^\mu)$

- eqs. de movimento (254.3):

$$\mu = 0: \quad \frac{\partial \mathcal{H}}{\partial \Phi} - \partial_j \left(\frac{\partial \mathcal{H}}{\partial (\partial_j \Phi)} \right) = -\partial_t \pi_0 = 0 \quad (255.2)$$

$$\mu = i: \quad - \frac{\partial \mathcal{H}}{\partial \pi_i} = \partial_t A_i \quad (255.3)$$

$$\frac{\partial \mathcal{H}}{\partial A_i} - \partial_j \left(\frac{\partial \mathcal{H}}{\partial (\partial_j A_i)} \right) = + \partial_t \pi_i \quad (255.4)$$

notar sinais!

famos que:

$$\text{Eq. (255.2): } \rho - \partial_j (c \pi_i) = 0 \rightarrow \vec{\nabla} \cdot \vec{\pi} = \frac{1}{c} \rho \quad (255.5)$$

$$\text{Eq. (255.3): } - (4\pi c^2 \pi_i + c \partial_i \Phi) = \partial_t A_i$$

$$\hookrightarrow 4\pi c \vec{\pi} = -\vec{\nabla} \Phi - \frac{1}{c} \partial_t \vec{A} \quad (255.6)$$

como $(\vec{\nabla} \times \vec{A})^2 = \epsilon_{k\ell m} \epsilon_{k\ell p q} (\partial_\ell A_m)(\partial_p A_q) =$

$$= (\partial_\ell A_m)(\partial_\ell A_m) - (\partial_\ell A_m)(\partial_m A_\ell)$$

Eq. (255.4) : $-\frac{1}{c} \vec{J}_i - \partial_j (\partial_j A_i - \partial_i A_j) \frac{1}{4\pi} = \partial_t \vec{\pi}_i$

$$\partial_j (\partial_i A_j - \partial_j A_i) - 4\pi \partial_t \vec{\pi}_i = \frac{4\pi}{c} \vec{J}_i$$

$$\underbrace{\partial_j (\partial_i A_j - \partial_j A_i)}_{(\vec{\nabla} \times (\vec{\nabla} \times \vec{A}))_i}$$

$$\hookrightarrow \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) - 4\pi \partial_t \vec{\pi} = \frac{4\pi}{c} \vec{J} \quad (256.1)$$

notas:

$$\cdot \vec{\nabla} \times \text{Eq. (255.6)} : \vec{\nabla} \times (4\pi c \vec{\pi}) = -\frac{1}{c} \partial_t (\vec{\nabla} \times \vec{A}) \quad (256.2)$$

$$\cdot \vec{\nabla} \cdot \text{Eq. (256.2)} : \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0 \quad (256.3)$$

notas : identificando $\vec{E} = 4\pi c \vec{\pi}$

\hookrightarrow Eqs. (255.5), (256.1) - (256.3) : eqs. de Maxwell !

Obs.: no formalismo Hamiltoniano

$\partial_t \phi_i \rightarrow$ substituído por π_i

mas $\partial_j \phi_i$ preservado, i.e., temos uma assimetria no tratamento das variáveis tempo e espaço

\hookrightarrow formalismo Hamiltoniano não é adequado p/ uma formulação covariante !